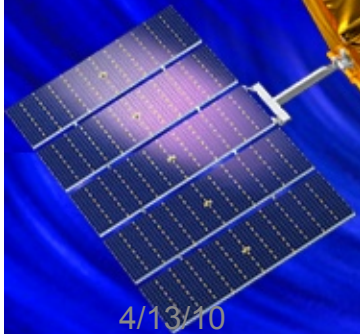


# The Requirements for Calibrating an X-ray Polarimeter

Keith Jahoda  
IACHEC 2010 Woods Hole, MA

**GEMS**  
Gravity and Extreme Magnetism SMEX



4/13/10

IACHEC 2010, Woods Hole



*Orbital*

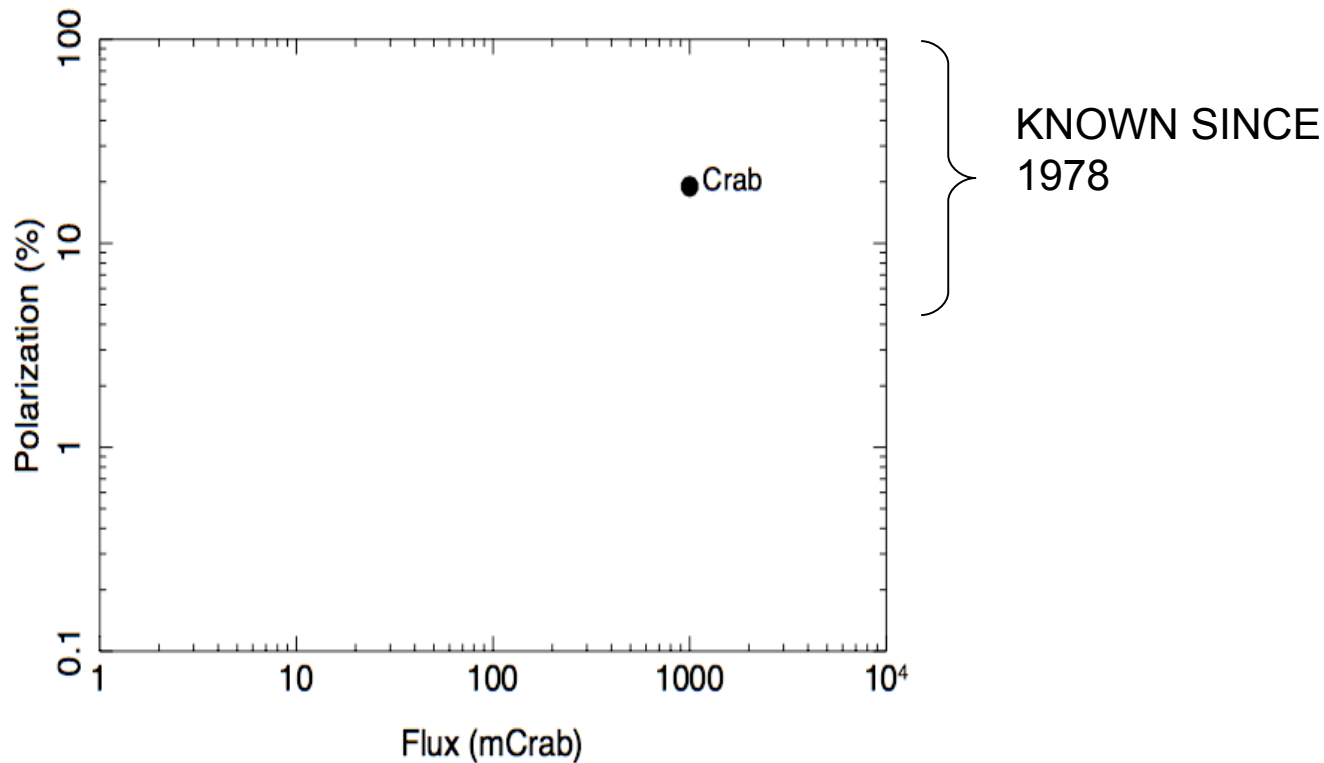
**ATK**



# X-ray Polarimetry

- Observational Status
- Photoelectric polarimetry basics
- Time projection detector concept
- Gravity and Extreme Magnetism Small Explorer mission
  - Expected Sensitivity and Results
    - Demonstrate the wisdom of including Polarimetry on IXO
  - Calibration needs and plans

# Status of X-ray Polarimetry



But interest remains high among theorists and experimentalists:

“X-ray Polarimetry Workshop”, Stanford, Feb 9-11, 2004

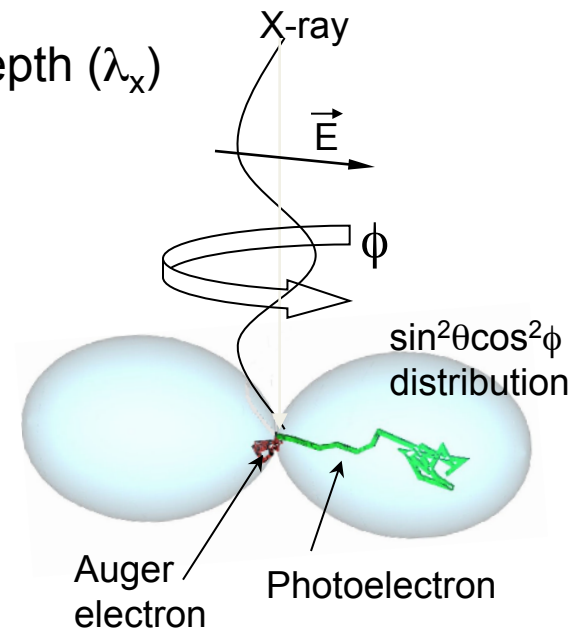
[http://www-conf.slac.stanford.edu/xray\\_polar/talks.htm](http://www-conf.slac.stanford.edu/xray_polar/talks.htm)

“The Coming Age of X-ray Polarimetry”, Rome, April 27-30 2009

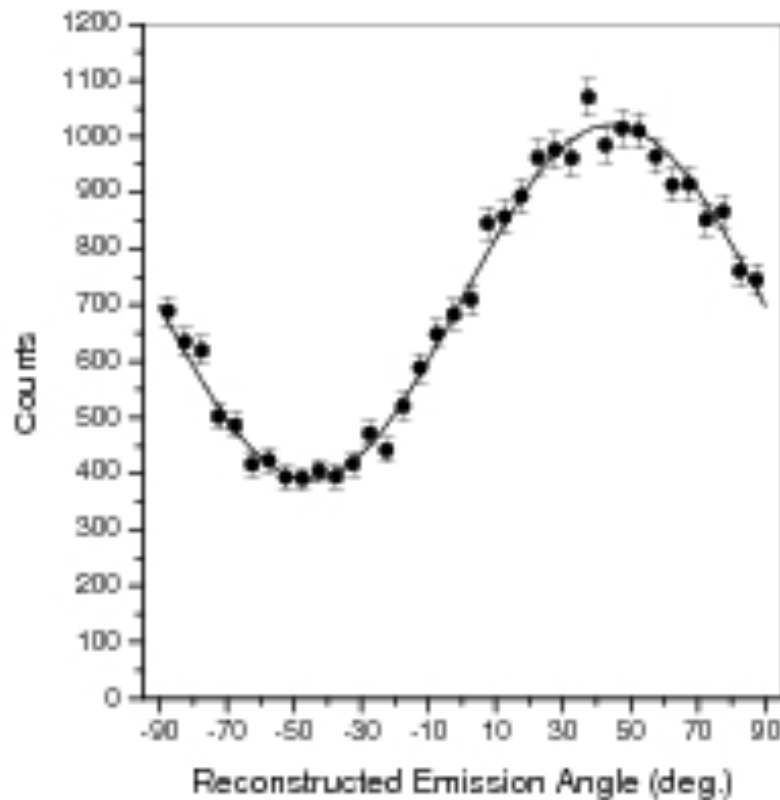
<http://projects.iasf-roma.inaf.it/xraypol/xraypol.htm>

# Photoelectric X-ray Polarimetry

- **Exploits:** strong correlation between the X-ray electric field vector and the photoelectron emission direction
- **Advantages:** dominates interaction cross section below 100keV
- **Challenge:**
  - Photoelectron range  $< 1\%$  X-ray absorption depth ( $\lambda_x$ )
  - Photoelectron scattering mfp  $< e^-$  range
- **Requirements:**
  - Accurate emission direction measurement
  - Good quantum efficiency
- **Ideal polarimeter:** 2d imager with:
  - resolution elements  $\sigma_{x,y} < e^-$  mfp
  - Active depth  $\sim \lambda_x$
  - $\Rightarrow \sigma_{x,y} < \text{depth}/10^3$



# Modulation - Definitions



In practice, the distribution of estimated track directions, even for purely polarized input, is more complicated than a projection of the  $\sin^2\theta\cos^2\phi$  probability distribution.

$$N = A + B \cos^2 (\phi - \phi_0)$$

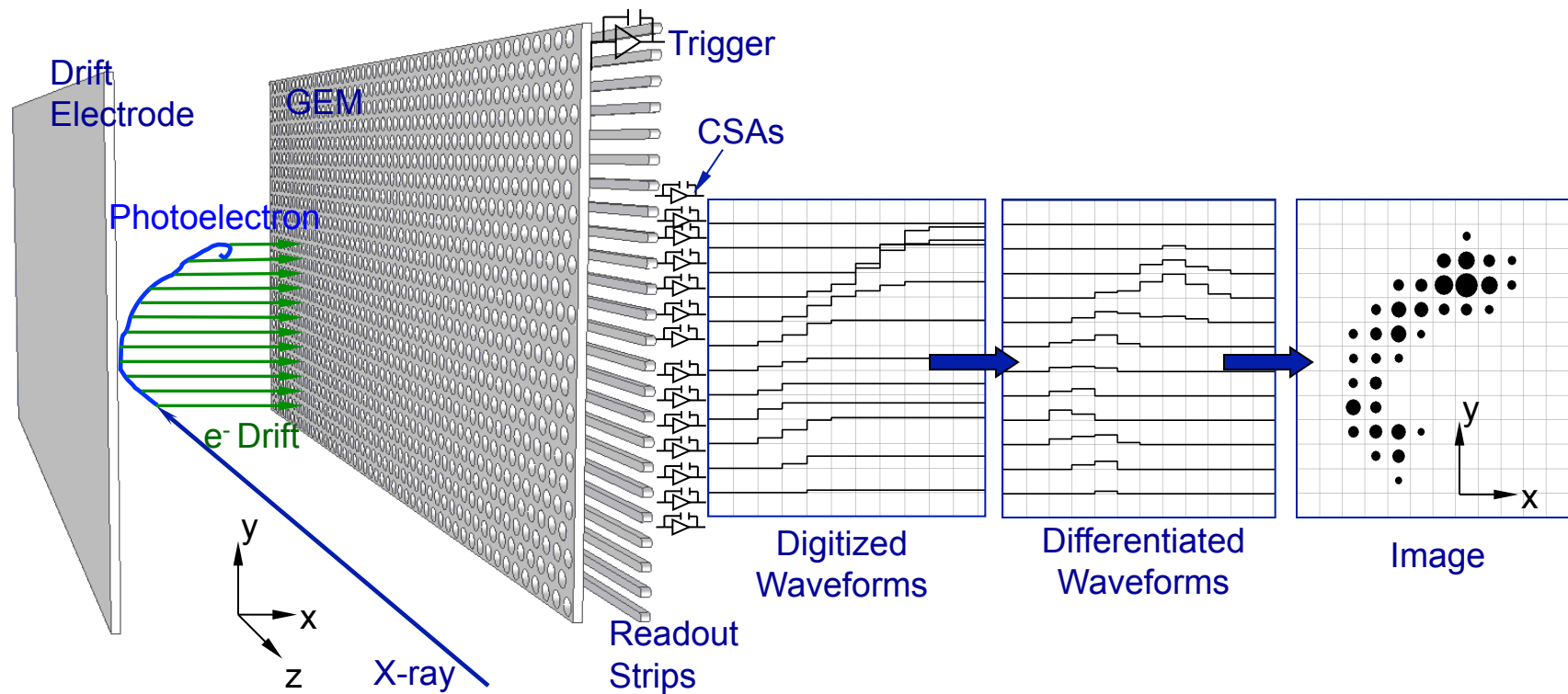
$$\mu = \frac{N_{\max} - N_{\min}}{N_{\max} + N_{\min}}$$

$$\mu = B / (2A + B)$$

$$MDP_{99} = \frac{4.29}{\mu R} \left( \frac{R + B}{T} \right)^{1/2}$$

# TPC Polarimeter Concept

- Drift direction is perpendicular to X-ray propagation so that diffusion is independent of the active depth
- Image in a plane normal to the detector elements using strip readout
- Pixels are formed by time projection, coordinates [arrival time, strip location]
- Drift height determined by collimation of beam

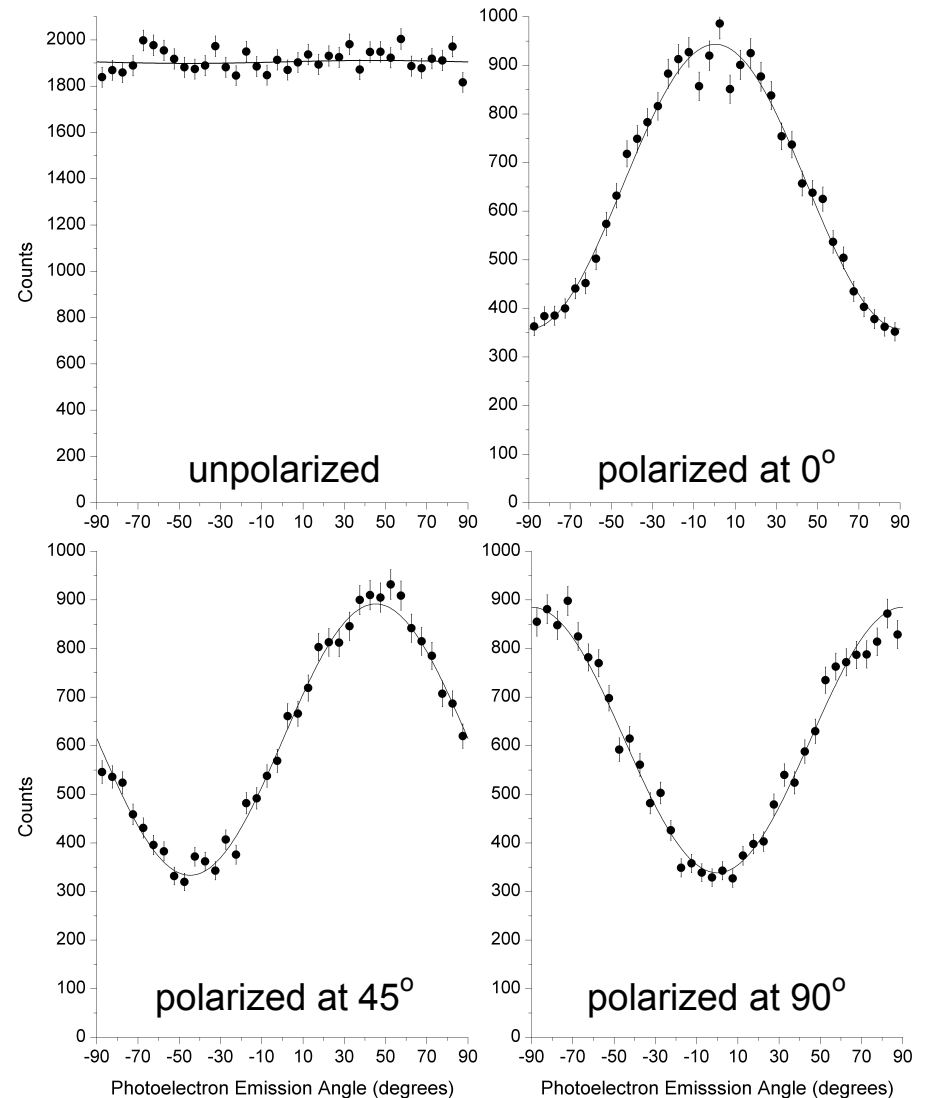


# Analysis and Results

- Histograms of reconstructed angles fit to expected functional form:  $N(\phi) = A + B \cos^2(\phi - \phi_0)$  where  $\phi_0$  is the polarization phase
- The modulation is defined as:  

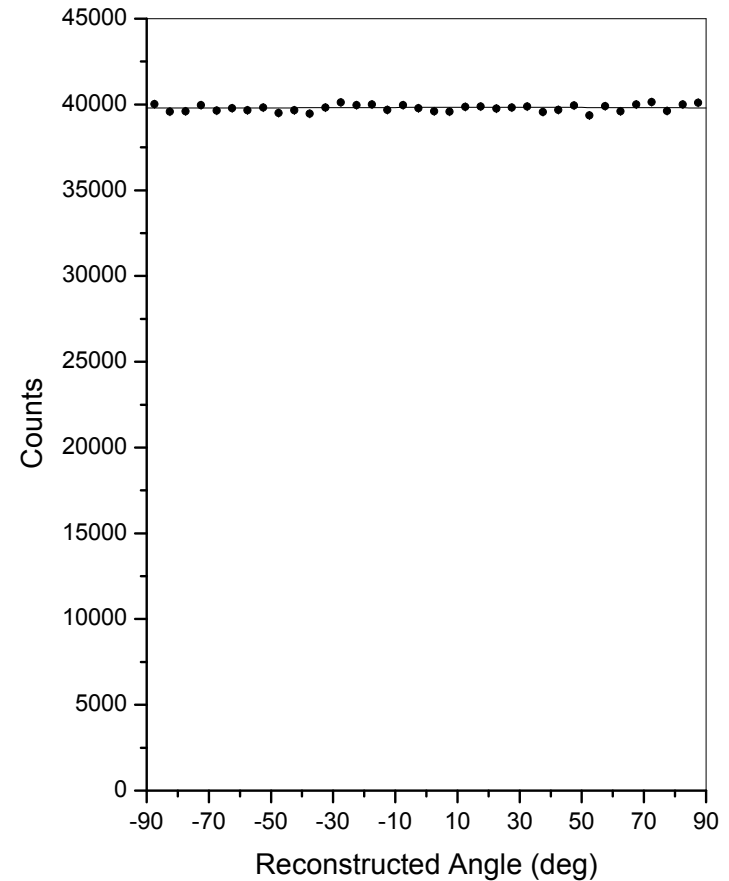
$$\mu = (N_{\max} - N_{\min}) / (N_{\max} + N_{\min})$$
- **Results:**
  - It's a polarimeter
  - Uniform response
  - No false modulation
- Black et al. (2007) NIM A, 581, 755

Polarization Phase	Measured Parameters		
	Modulation (%)	Phase (degrees)	$\chi^2_v$
unpolarized	$0.49 \pm 0.54$	$44.6 \pm 28.7$	1.2
$0^\circ$	$45.0 \pm 1.1$	$0.3 \pm 0.6$	1.1
$45^\circ$	$45.3 \pm 1.1$	$45.2 \pm 0.6$	1.0
$90^\circ$	$44.7 \pm 1.1$	$-89.9 \pm 0.6$	1.4



# Response to unpolarized X-rays

- Histograms of reconstructed angles for unpolarized data.  $1.4 \times 10^6$  cts over 40 ks
- ~60 “spacecraft rotations”
- measured modulation
  - Amplitude 0.05% +/- 0.12%
  - $\phi_0 = 20.9 \pm 73.9$  deg
  - $\chi^2 = 1.05 / \text{dof}$

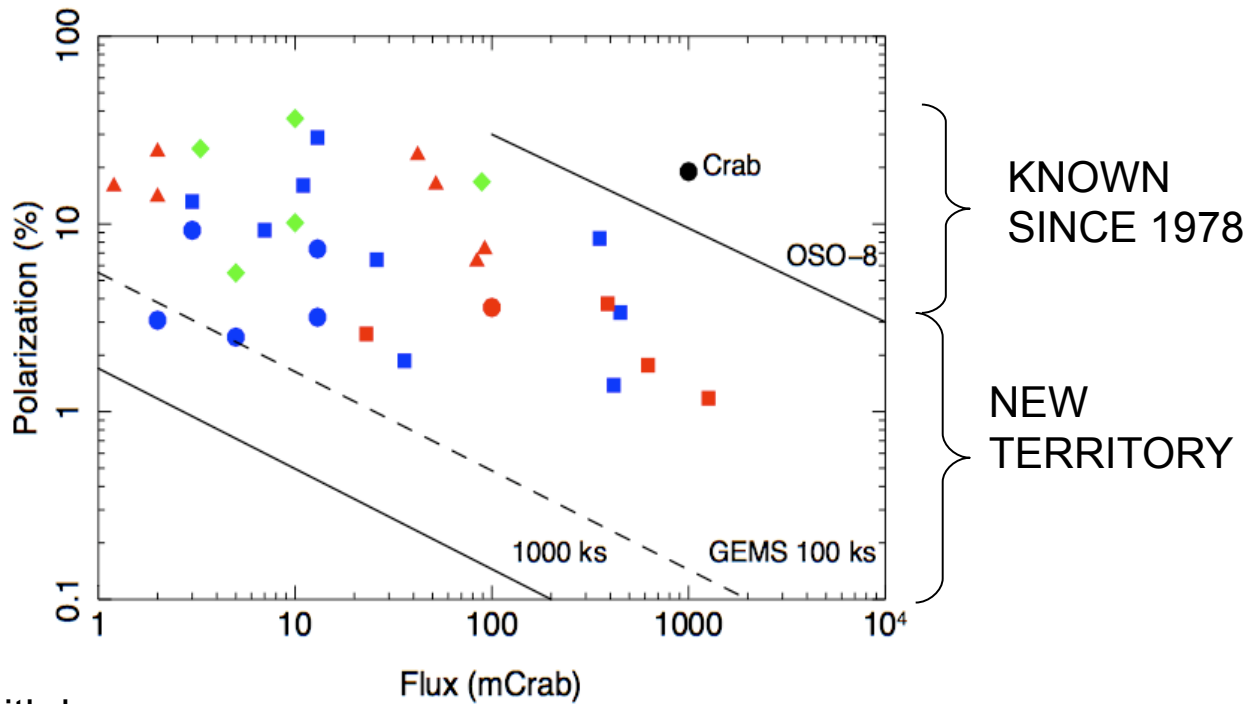




# Gravity and Extreme Magnetism Small Explorer Concept

- The Time Projection Polarimeter is the heart of the Gravity and Extreme Magnetism Small Explorer
  - Currently in Phase B
  - Launch in 2014
- Rotation of three-axis stabilized spacecraft for low false modulation due to instrumental systematic error
- Full sky visibility; ~300 sources accessible, each for ~ 8 weeks every 6 months
- Straightforward operations concept
- 9 month program of 35 targets
  - Black Holes, Neutron Stars, SNR
- No consumables, lifetime  $\geq 2$  yr





Targets with known  
fluxes and polarization  
estimates

**Black holes**

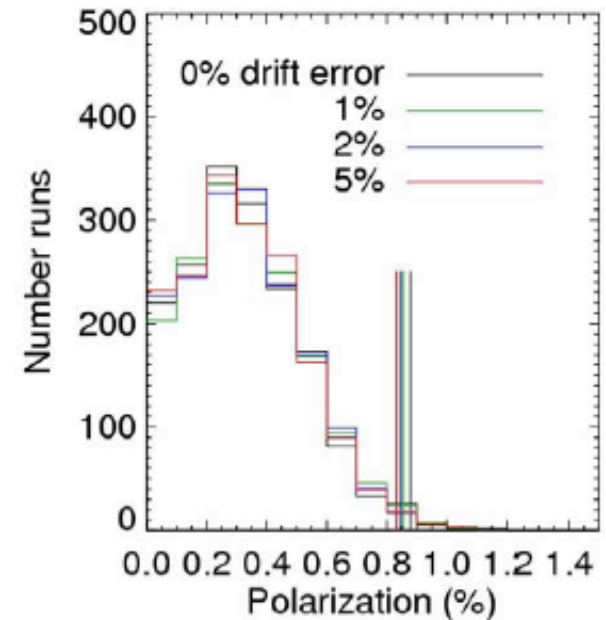
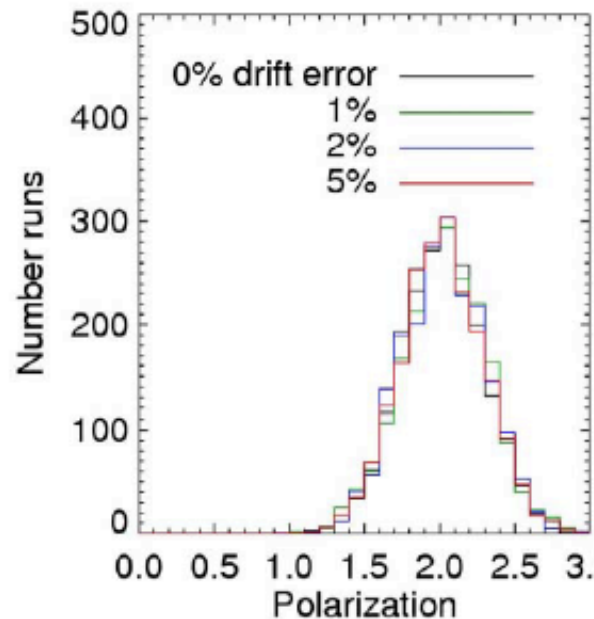
**Neutron stars**

**Supernova remnants**

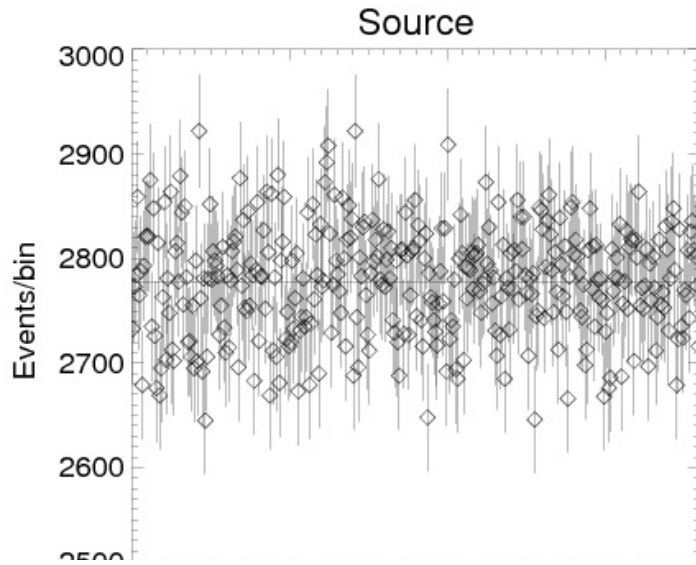
# Benefits of Rotation

- Simulations with  $10^6$  photons/run ( $\mu \sim 0.5$ ,  $MDP < 0.01$ ) show the power of spacecraft rotation
- PROCEDURE

- Generate photons
- Move photon E-field into detector frame
- Generate photoelectron direction with  $\cos^2(\phi)$  distribution
- Distort (by stretching) one axis
- Measure the distorted direction
- Map the photoelectron direction back onto the sky



- RESULTS: Spacecraft rotation removes the effects of detector asymmetries

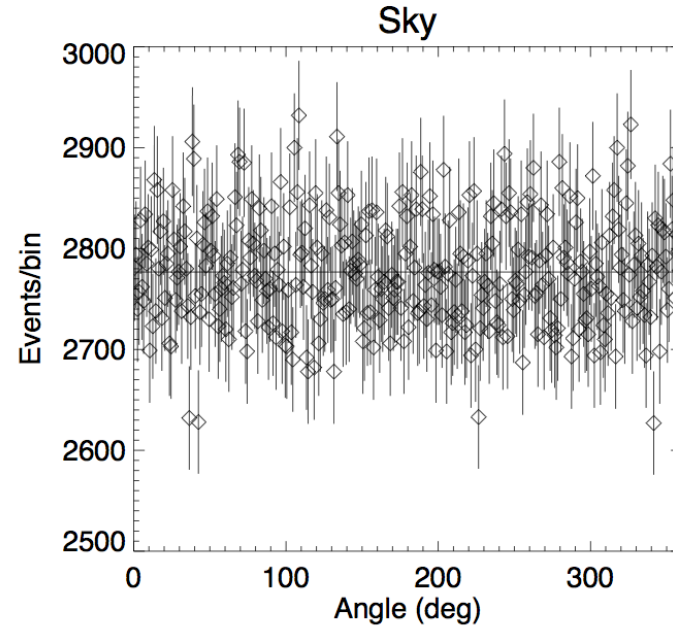
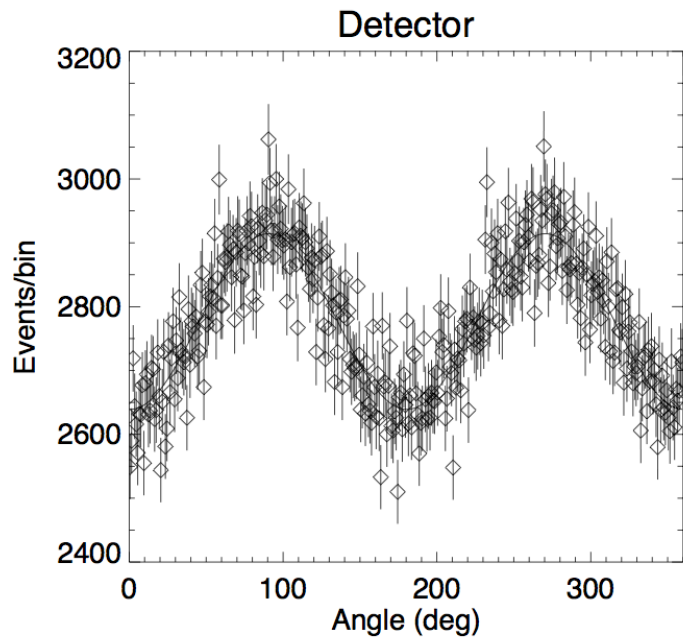


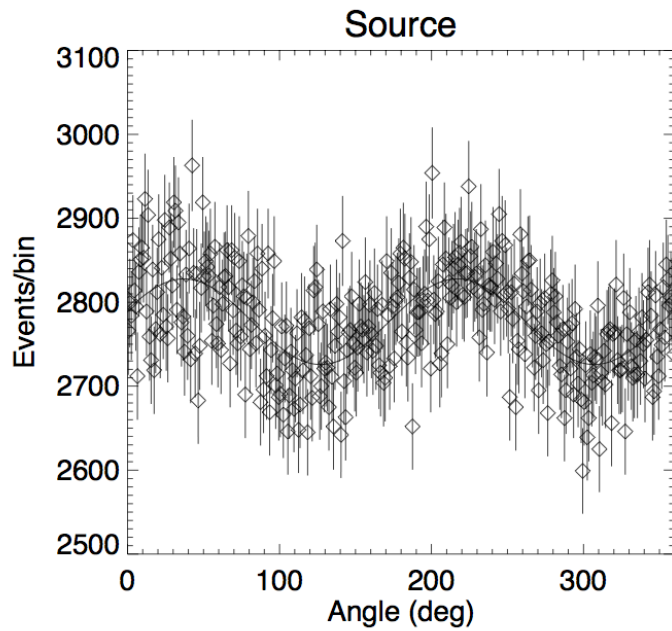
Source is unpolarized

$$\mu = 0.5$$

$$N = 10^6$$

$$T = 10^5 \text{ sec } (\sim 160 \text{ rotations})$$



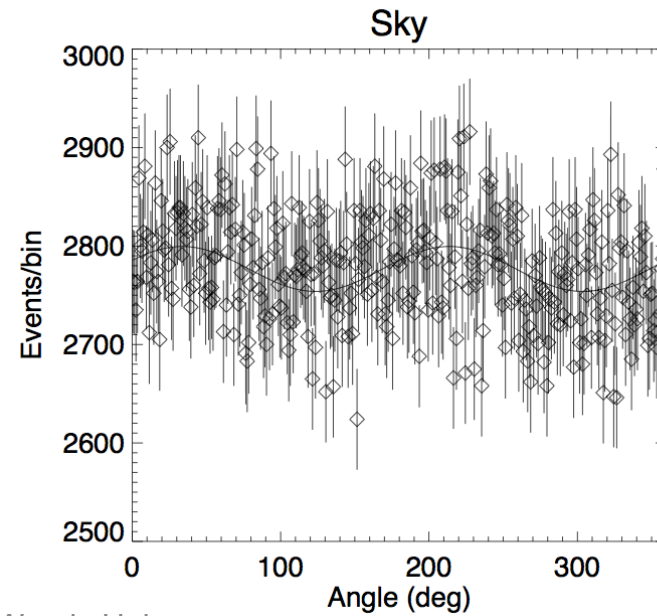
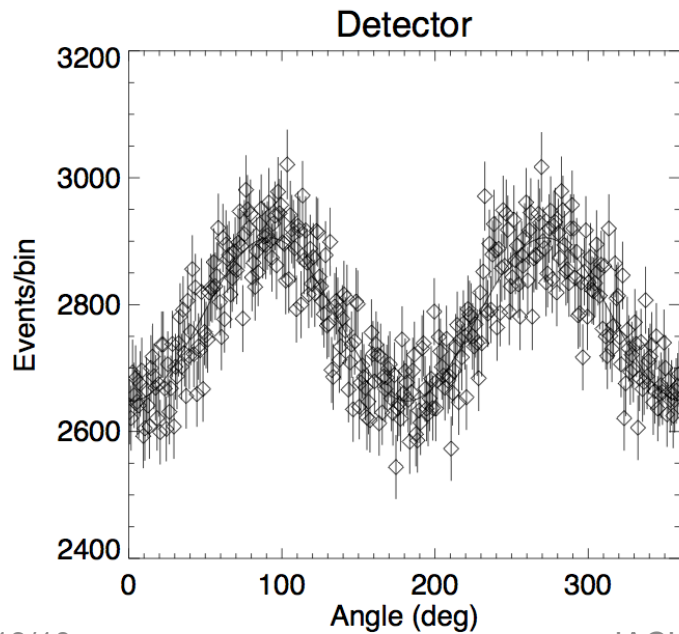


Source has 2% polarization

$$\mu = 0.5$$

$$N = 10^6$$

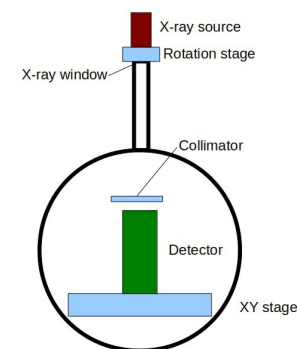
$$T = 10^5 (\sim 160 \text{ rotations})$$



# Calibration Needs

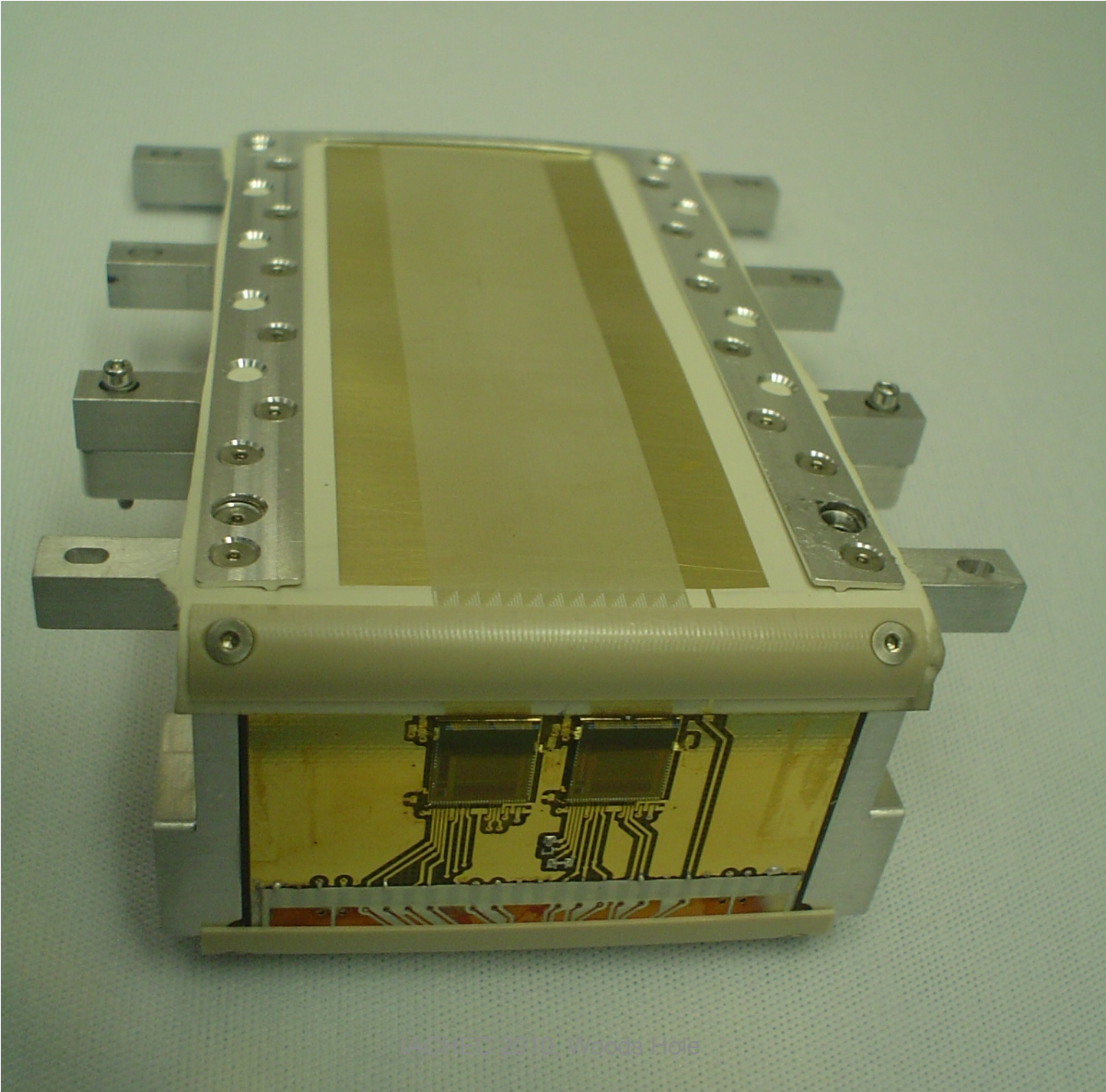
- Verification of Physical and Empirical models for
  - $\mu_{100}(E, x, y, z)$  - good precision
  - $\mu_0(E, x, y, z)$  - **high** precision
  - $A_{\text{eff}}(E)$ , efficiency (E), redistribution (E)
- Tools
  - At U. Iowa: collimated pencil beams
    - Unpolarized at 2.7 keV, 5-8 keV broad band
    - Polarized at 2.7, 3.7, 4.5, 6.4, 8.0 keV
    - Detector in vacuum
  - At GSFC: collimated and broad band beams
    - 5.9 keV from  $\text{Fe}^{55}$
    - 2.7 and 4.5 keV
    - Detector in air
  - At BNL: collimated and polarized beam at “all” energies

Calibration  
beam line



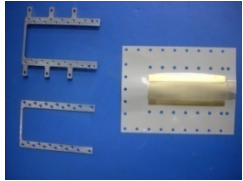
# 2010 Activities

- Construction of Engineering Test Unit
  - Engineering tests
  - Performance tests
    - Uniformity
    - Sensitivity
    - Background rejection
- Construction of U. Iowa calibration beam line
  - ETU performance tests, procedure development
- GEMS SRR
  - Requirements development and documentation

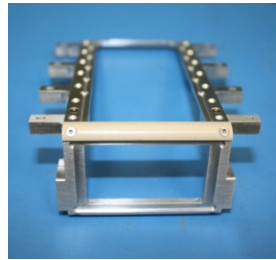
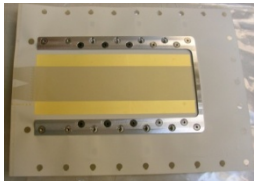
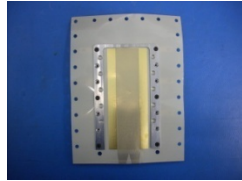




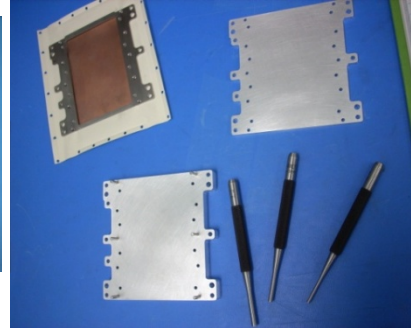
# GEM – ROB Hardware



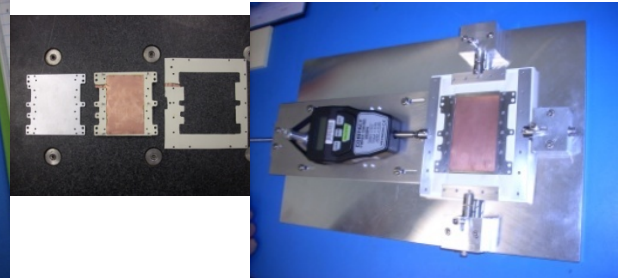
ROB framing technique



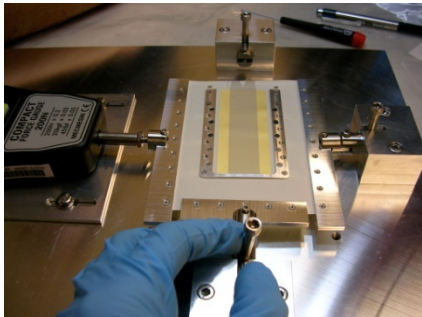
ROB Frame



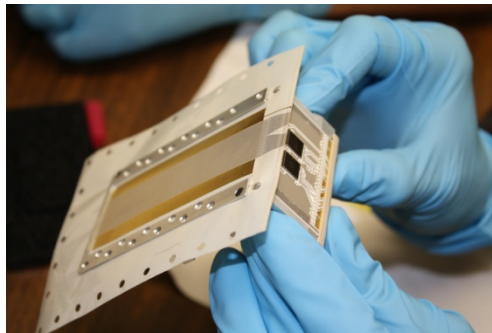
Fixture and Punch Parts



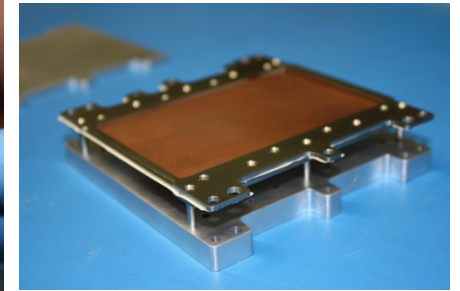
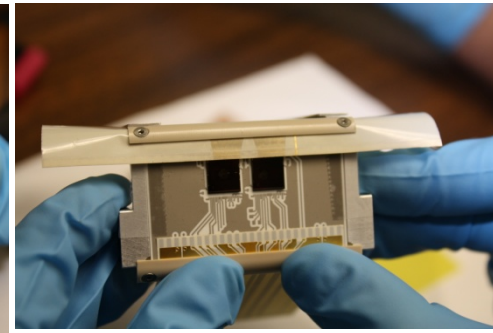
GSE fixture to be used to trim excess LCP from frame after mounting.



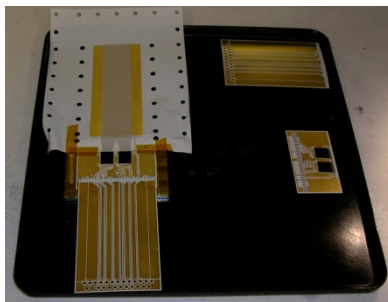
ROB stretching procedure



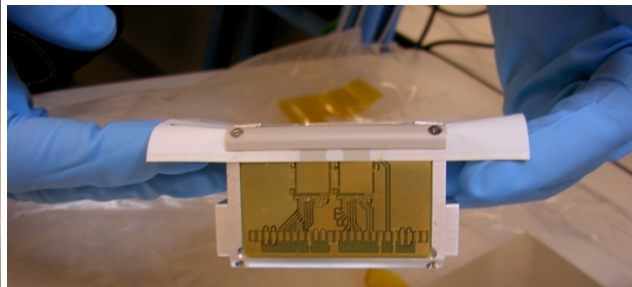
ROB Prototype Frame and Bracket



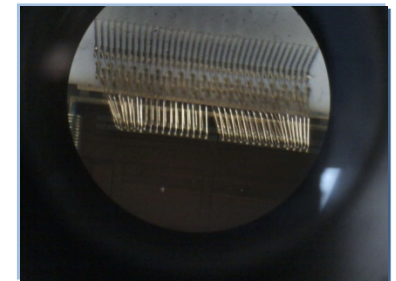
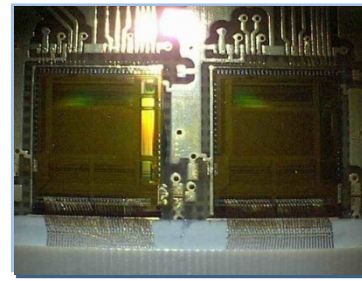
Prototype GEM Assembly



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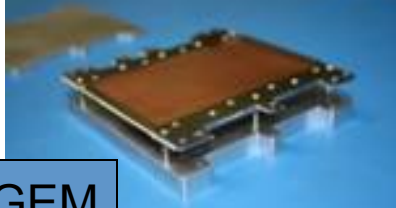
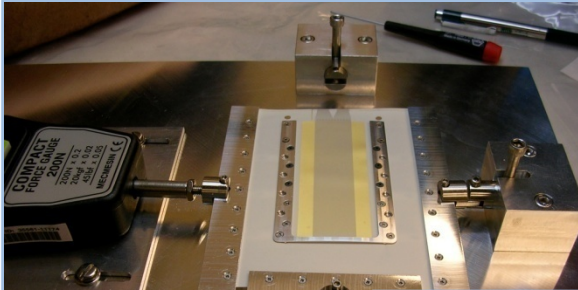


IACHEC 2010, Woods Hole  
ceramic board with wire bonding



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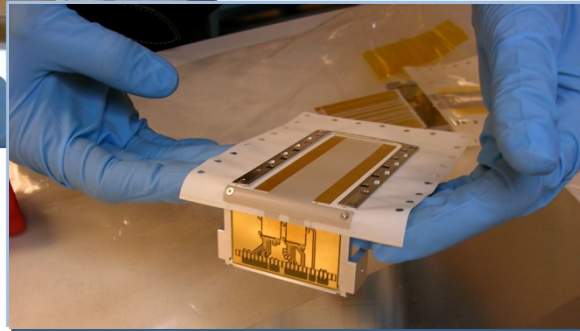
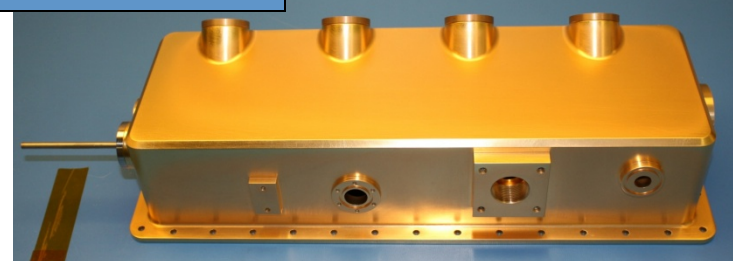
# ETU Hardware



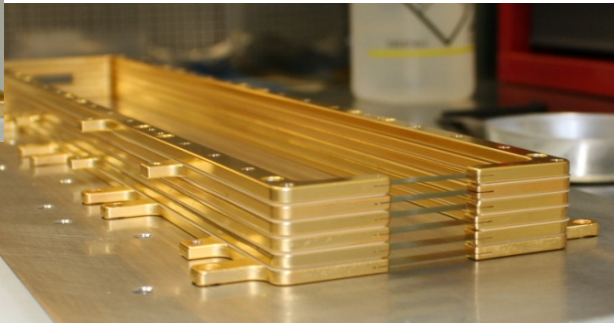
GEM



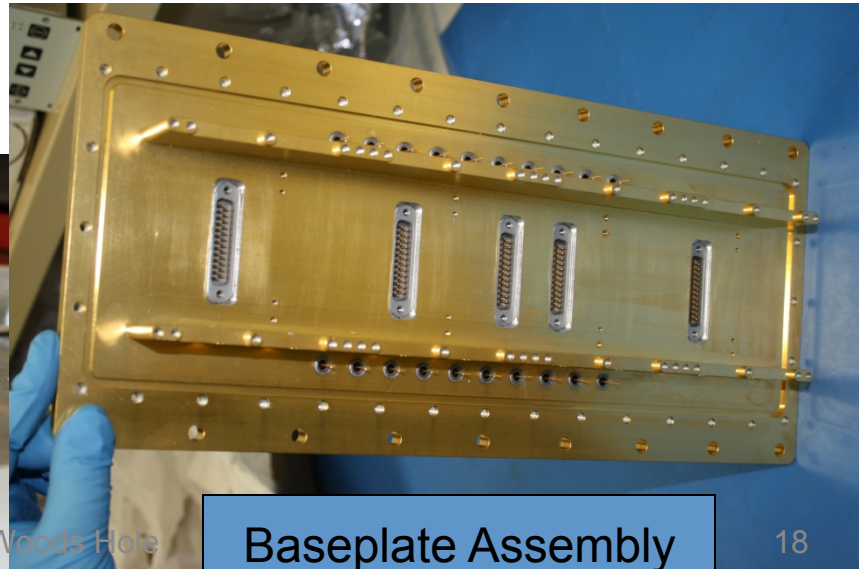
Cover Assembly



First Level in Assembly



Field Cage Assembly



Baseplate Assembly