

# Evaluation of the in-orbit pointing accuracy of XRISM

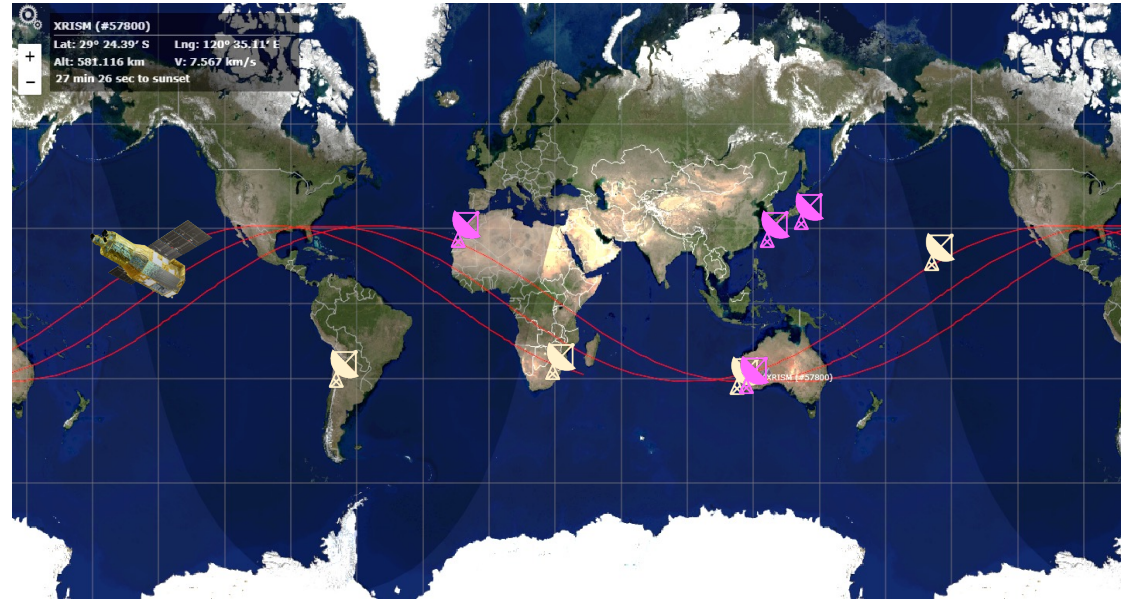
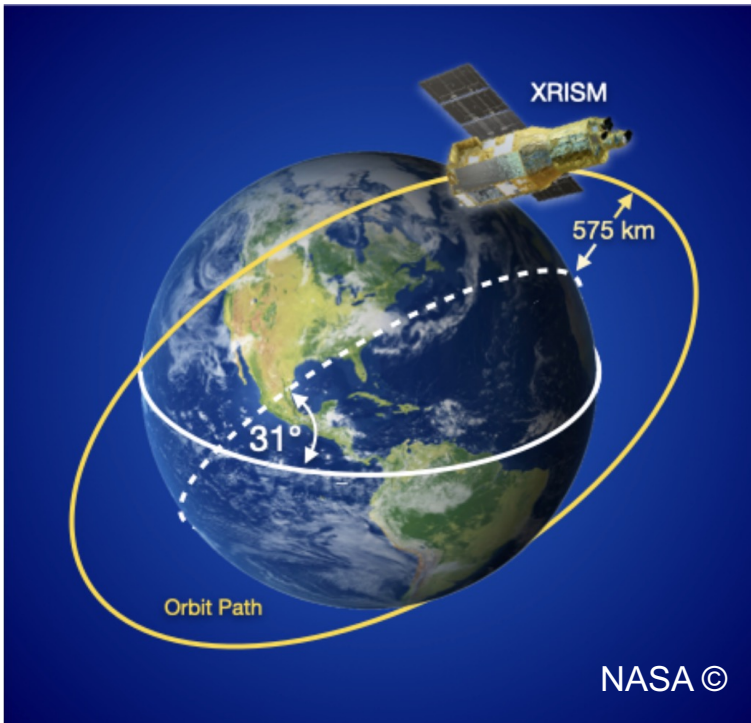
(15 May 2024, IACHEC)

Yoshiaki Kanemaru<sup>[1]</sup>,  
Ryo Iizuka<sup>[1]</sup>, Yoshitomo Maeda<sup>[1]</sup>, Kazuhiro Kiyokane<sup>[2]</sup>, Takashi Kominato<sup>[2]</sup>, Yuto Nihei<sup>[2]</sup>,  
Chikara Natsukari<sup>[1]</sup>, Shin Watanabe<sup>[1]</sup>, Manabu Ishida<sup>[1]</sup>,  
Takashi Okajima<sup>[3]</sup>, Takayuki Hayashi<sup>[3]</sup>, Kosuke Sato<sup>[4]</sup>, Yukikatsu Terada<sup>[1, 4]</sup>,  
and SOT members

([1]: ISAS/JAXA, [2] NEC, [3] GSFC/NASA, [4] Saitama University)

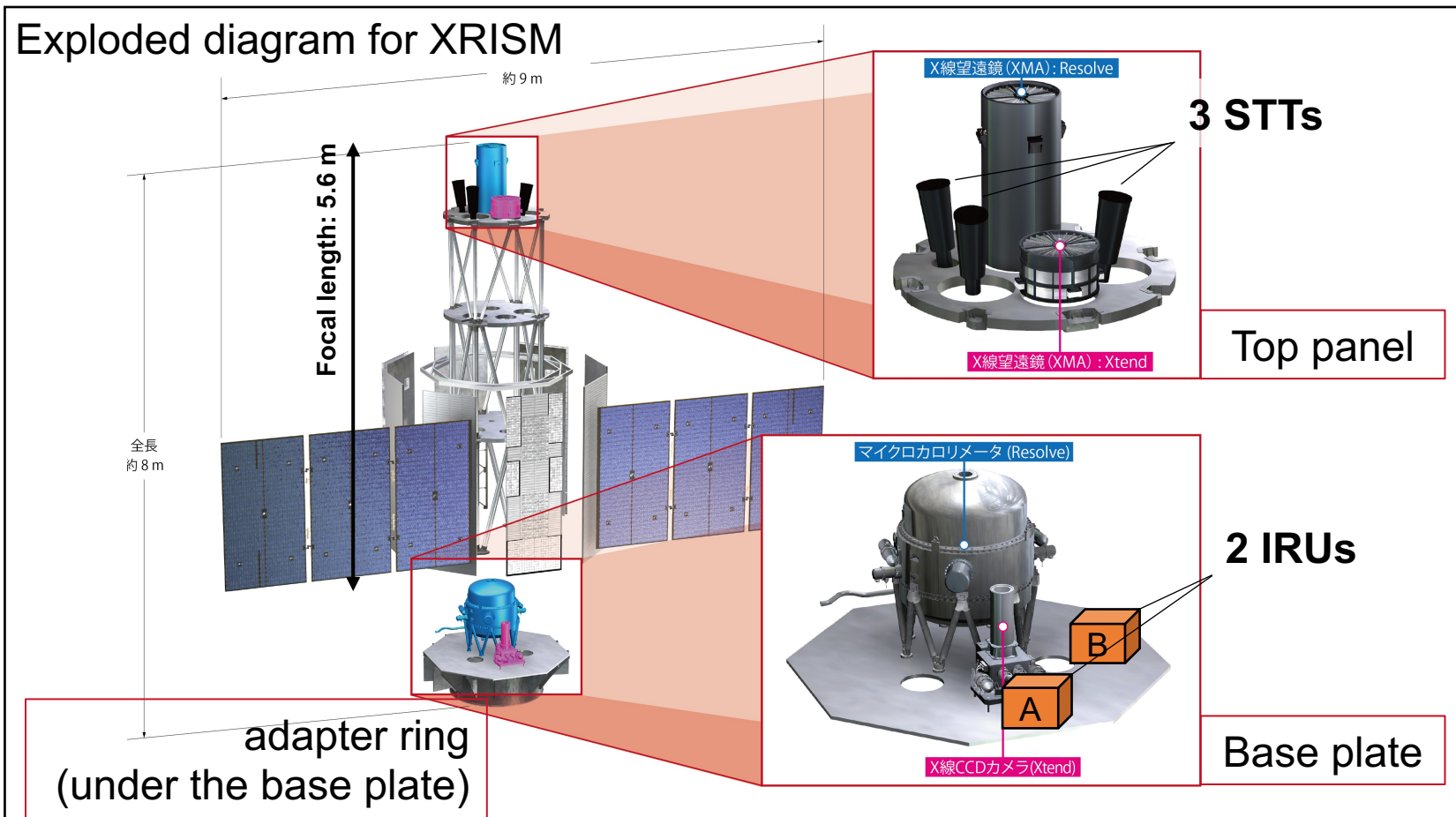
1. Introduction
2. Aimpoint search
3. Comparison of Resolve and Xtend
4. Control and Determination accuracy

# Introduction



- XRISM was successfully launched on 6 Sep 2023 (UTC).
  - Altitude: 575 km
  - Inclination angle: 31 degree
  - Orbital period: 96 min
- Almost all observations contain the earth occultation.

# Main components for pointing determination

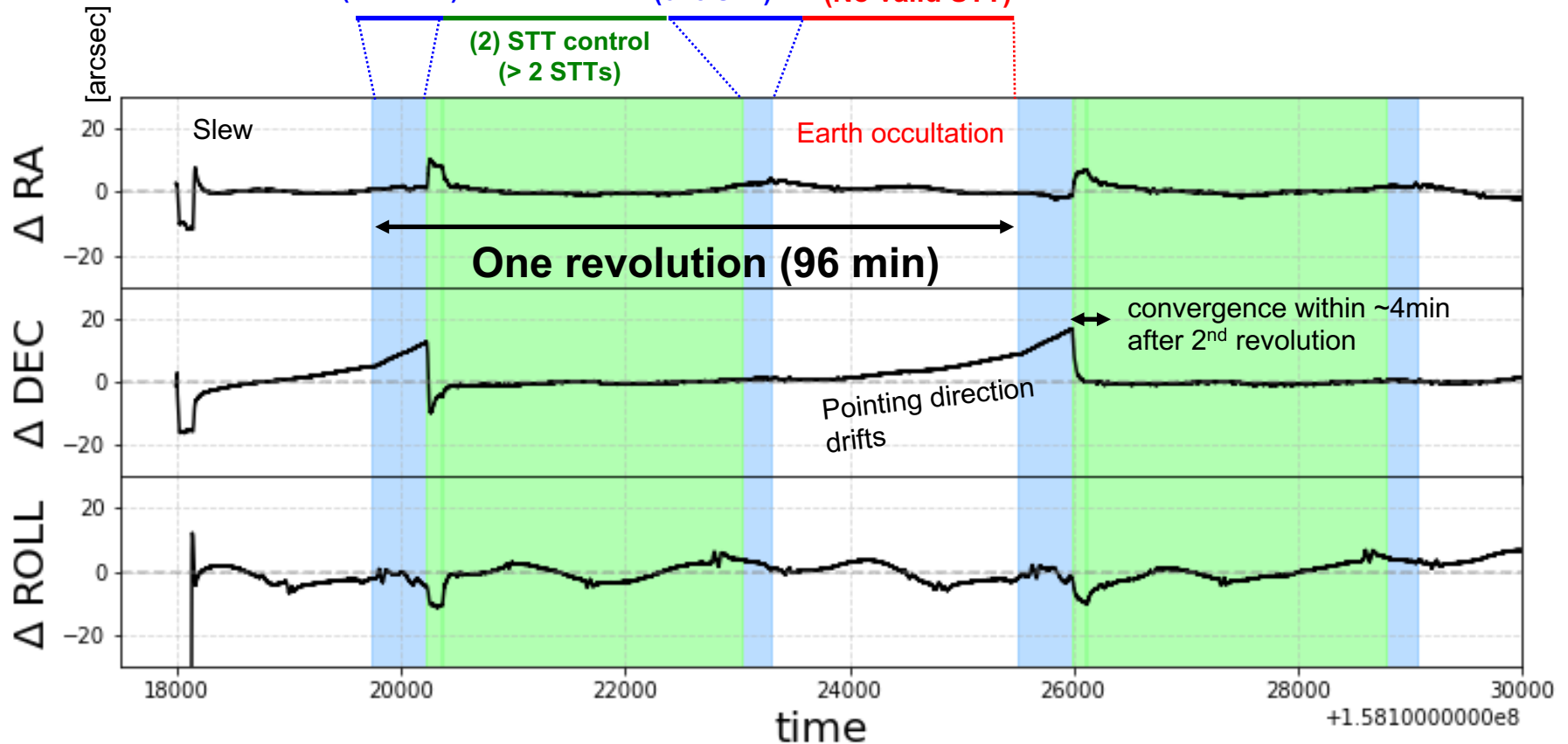


- XRISM carries three star trackers (STTs) on the top panel and two inertial reference units (IRUs) on the base plate. These components are mainly used for pointing determination.
- In the normal mode, the attitude is controlled using two STTs as long as there is no earth occultation blocking their FOV. If this condition isn't met, IRUs take over the attitude control.

# Typical attitude control cycle

Typical control cycle

(1) IRU control (one STT)      (3) IRU control (one STT)      (4) IRU control (No valid STT)  
(2) STT control (> 2 STTs)



Deviations from nominal RA, Dec, and Roll

- In the normal mode, the attitude is controlled using two STTs as long as there is no earth occultation blocking their FOV. If this condition isn't met, IRUs take over the attitude control.

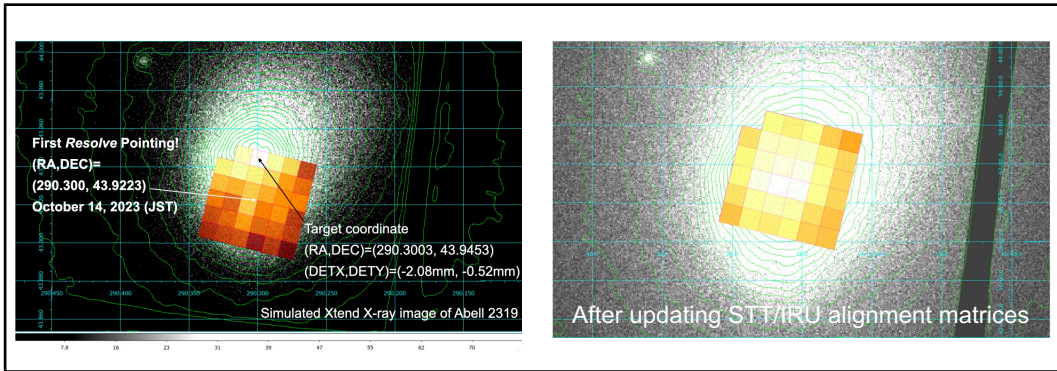
# Aimpoint search



- After the AOCS checkout phase, aimpoint search was performed twice.
- The objective is to calibrate and validate the aimpoint within a 1.5 mm (55") radius from the center of the array by updating onboard STT/IRU parameters.

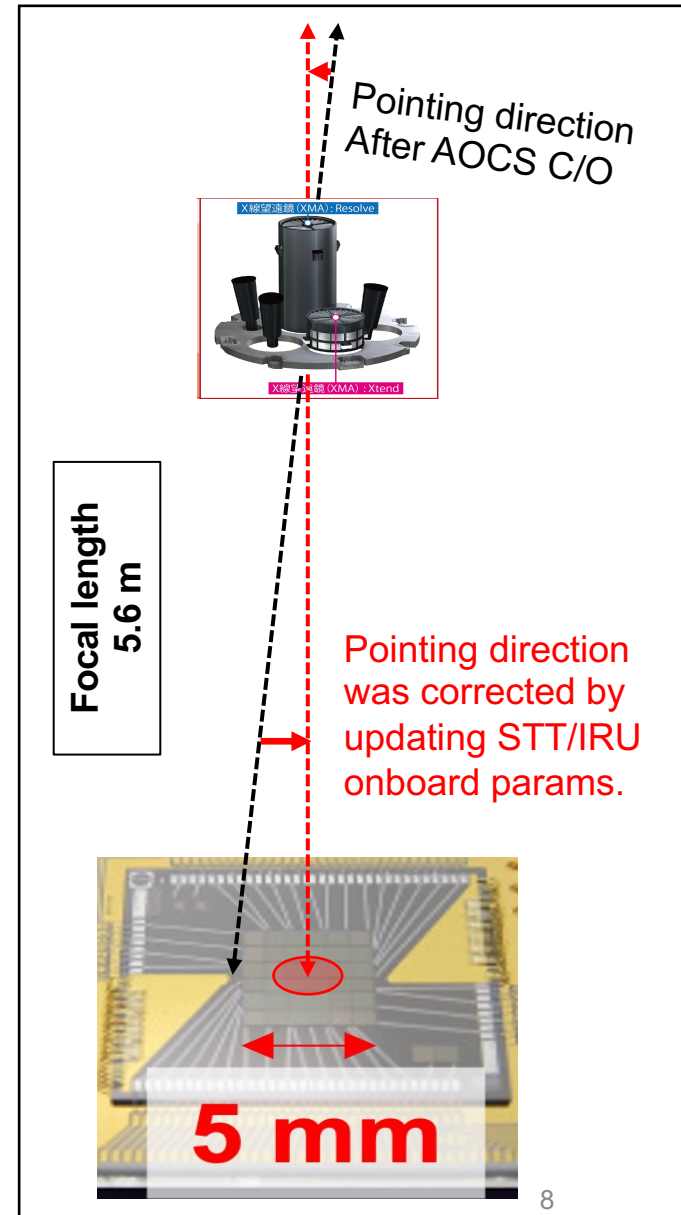
## • Aimpoint search 1

- **rough adjustment** by an extended source



## • Aimpoint search 2

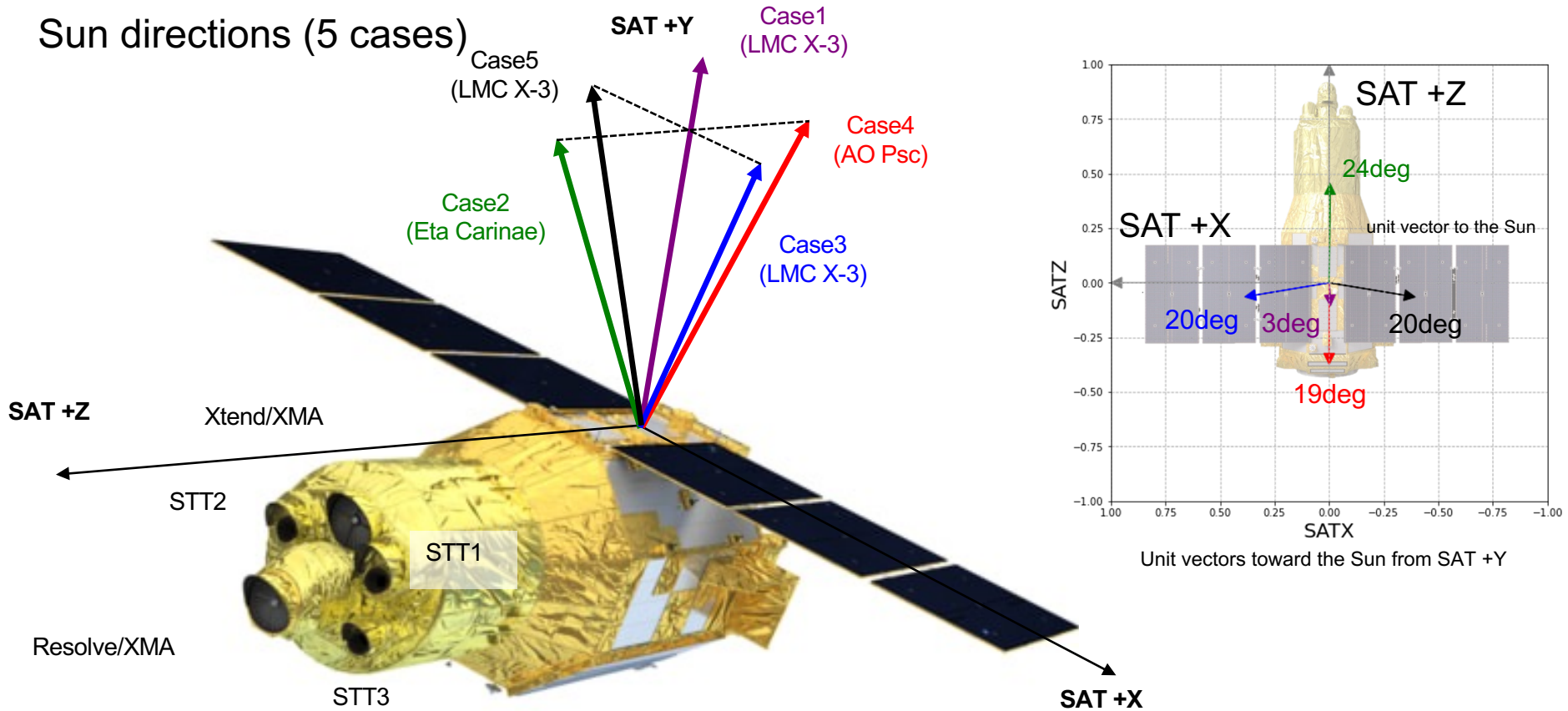
- **precise adjustment** and validation by point sources with different sun direction and STT combinations.





# Aimpoint search 2

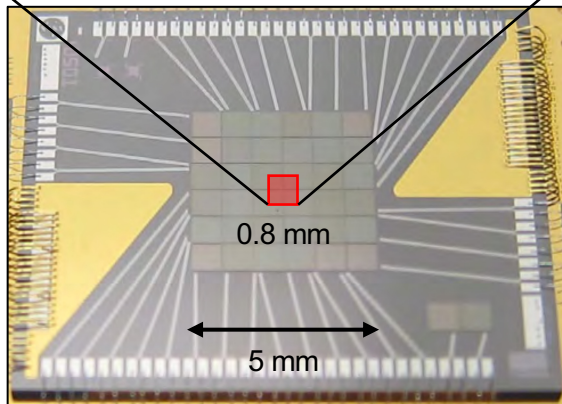
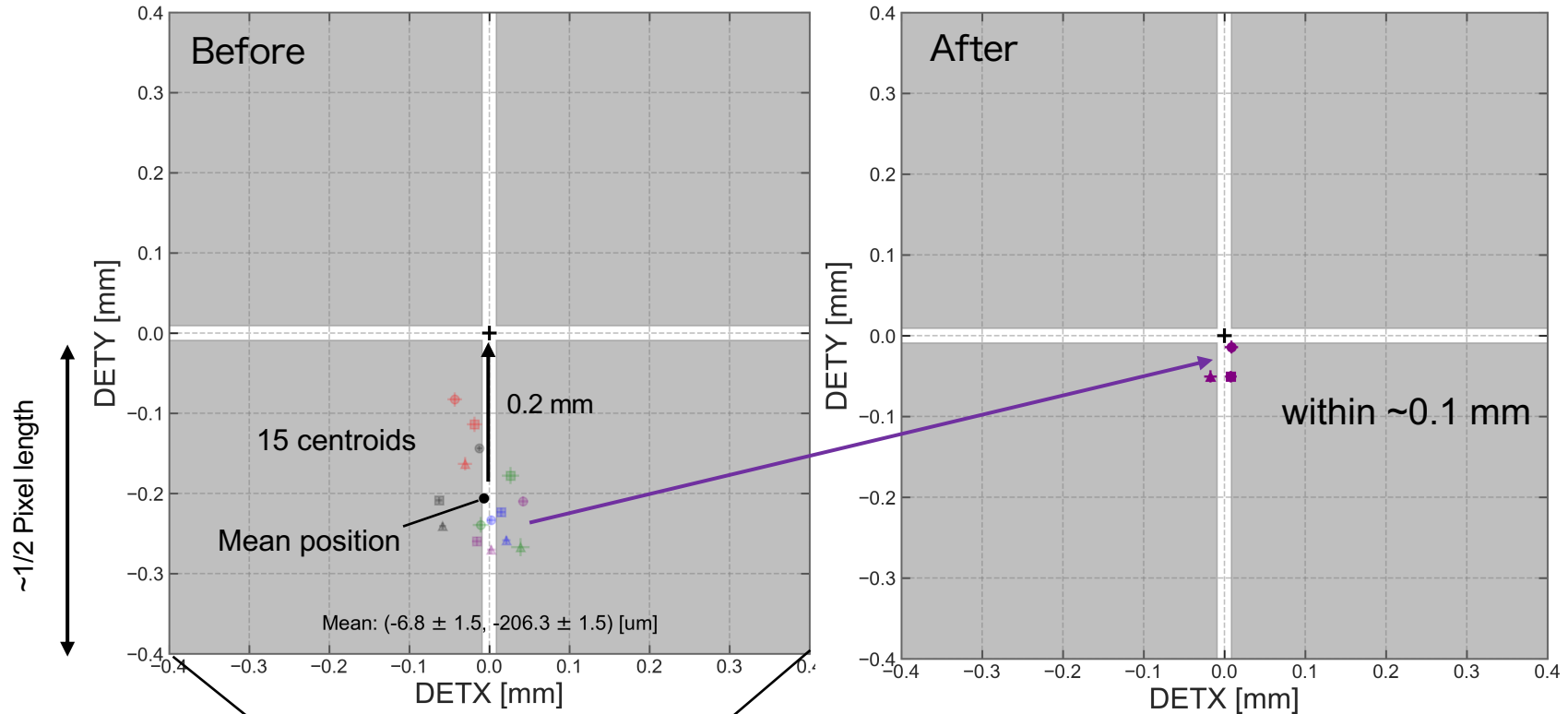
## Sun directions (5 cases)



- In aimpoint search 2, 15 patterns datasets are obtained to consider **(1) sun direction** (Thermal strains) and **(2) STT combinations** (STT biases)
- 5 sun directions  $\times$  3 STT combination = 15 patterns
  - Case 1, 3, 5: rotation about Sat +Z
  - Case 1, 2, 4: rotation about Sat +X



# Result of aimpoint search 2

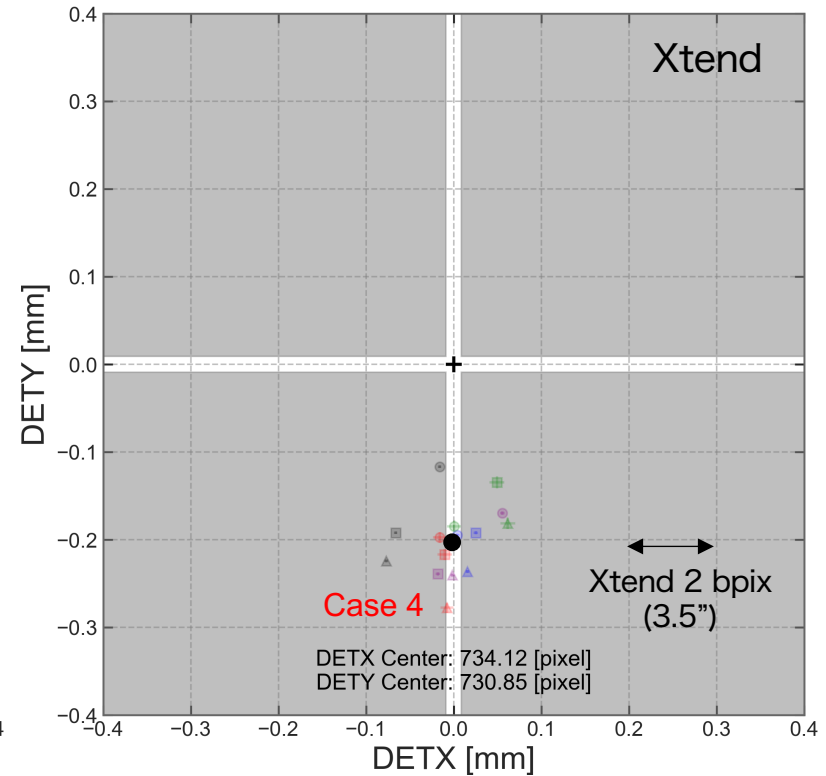
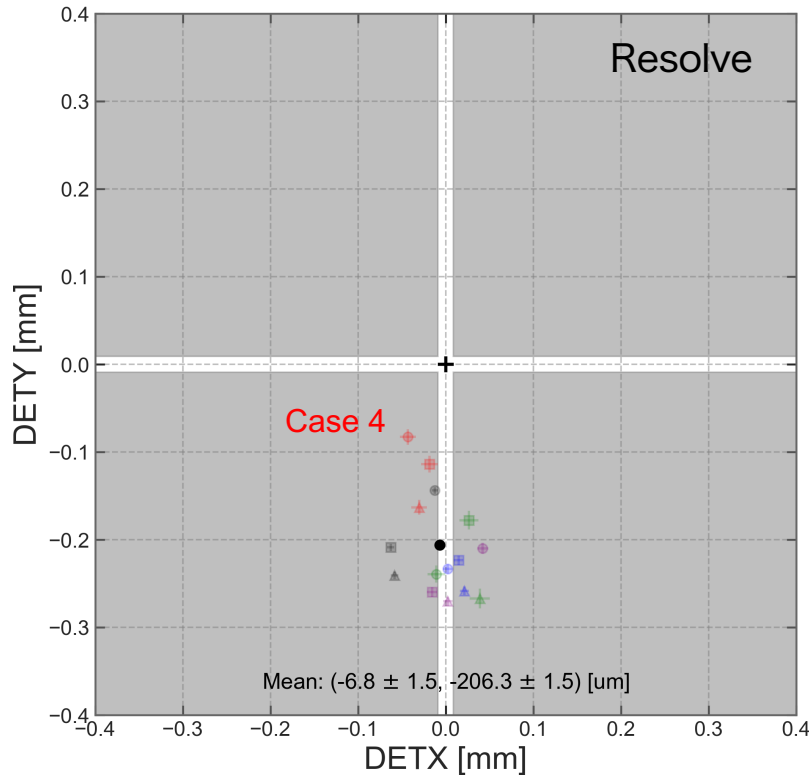


- The observed offset was (DETX, DETY) = (0.0 mm, -0.2 mm), and we updated STT/IRU onboard alignment matrices.
- The centroids of verification observations were located within 0.1 mm from the center. It satisfied the requirement of a 1.5 mm (55") radius.

1. The centroids of verification observations were located within 0.1 mm from the center of the array. It satisfied the requirement of a 1.5 mm (55") radius.
2. The **sun direction** and the **STT bias** can cause the aimpoint shift by ~0.1 mm in DET coordinates.
  - Although the **STT bias** can be mitigated in SKY coordinate by offline processing, the **sun direction's effect** cannot be corrected in SKY coordinate. The a few arcsec offset remains.

# Comparison of Resolve and Xtend

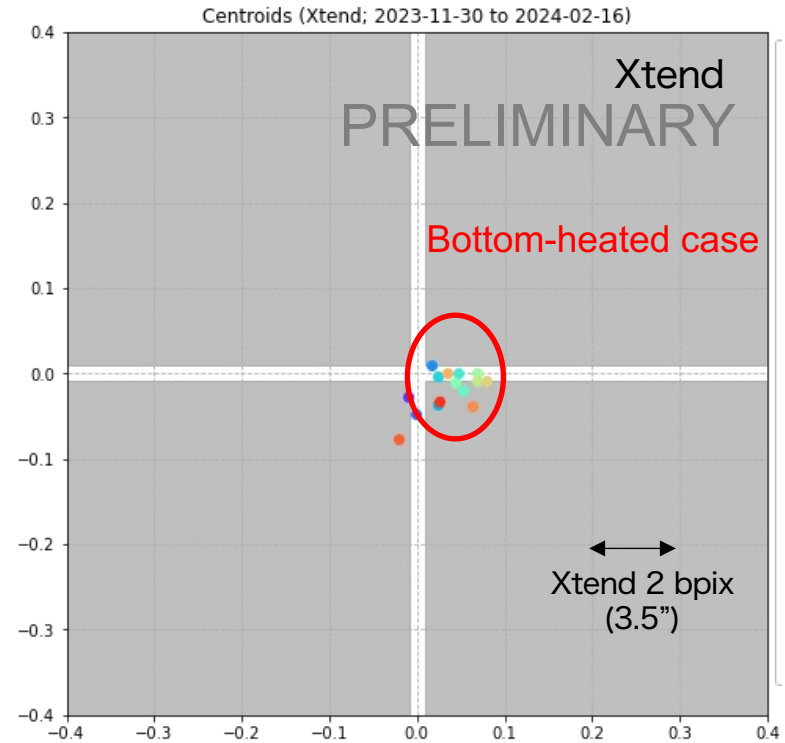
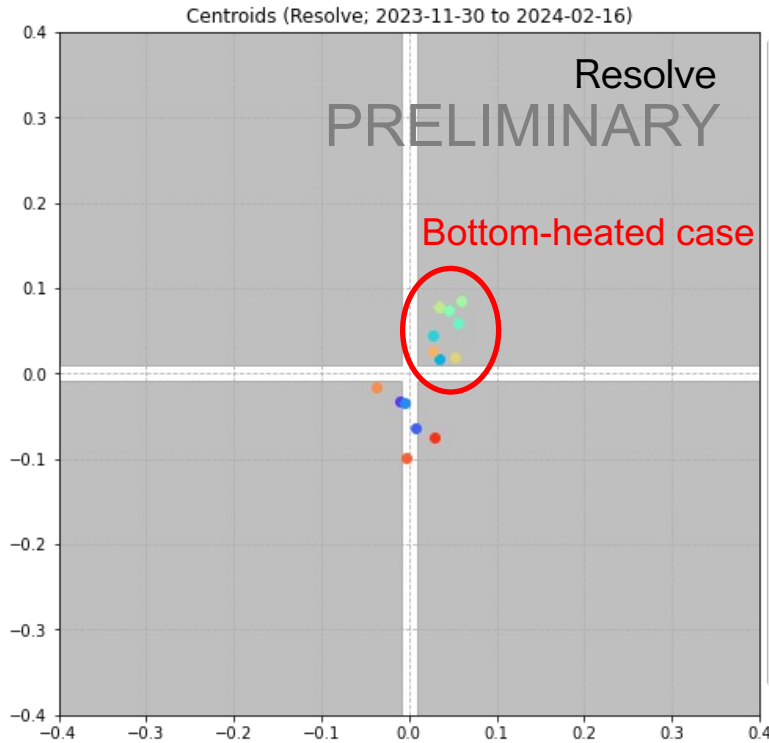
# Comparison of Resolve and Xtend



- Comparison of Resolve and Xtend

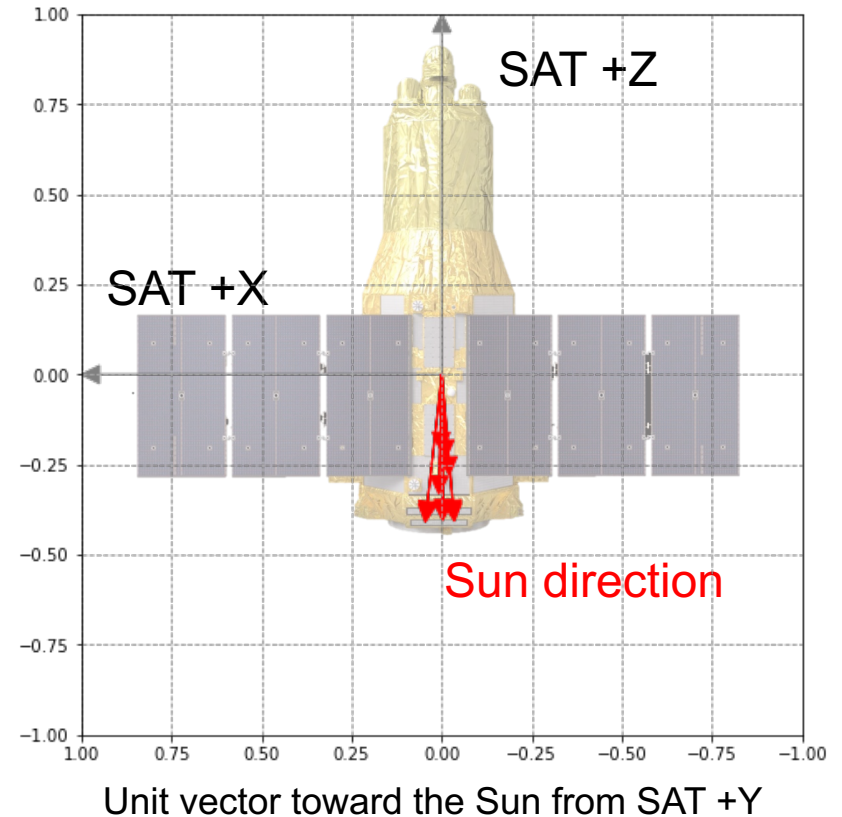
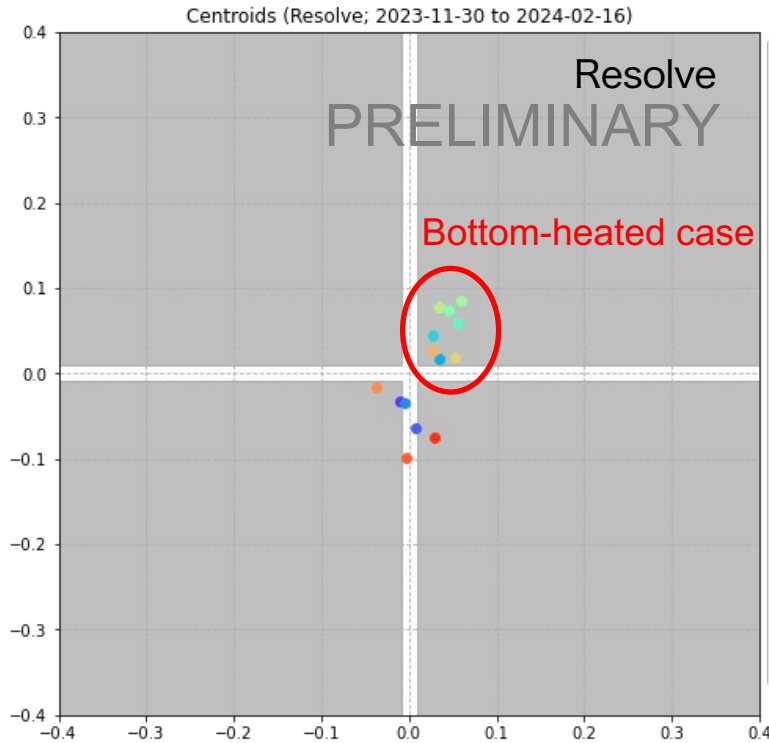
- Dataset: Aimpoint search observations
- The shift amounts and directions of Resolve and Xtend are similar, except for the **bottom-heated case (Case 4)**.

# Comparison of Resolve and Xtend



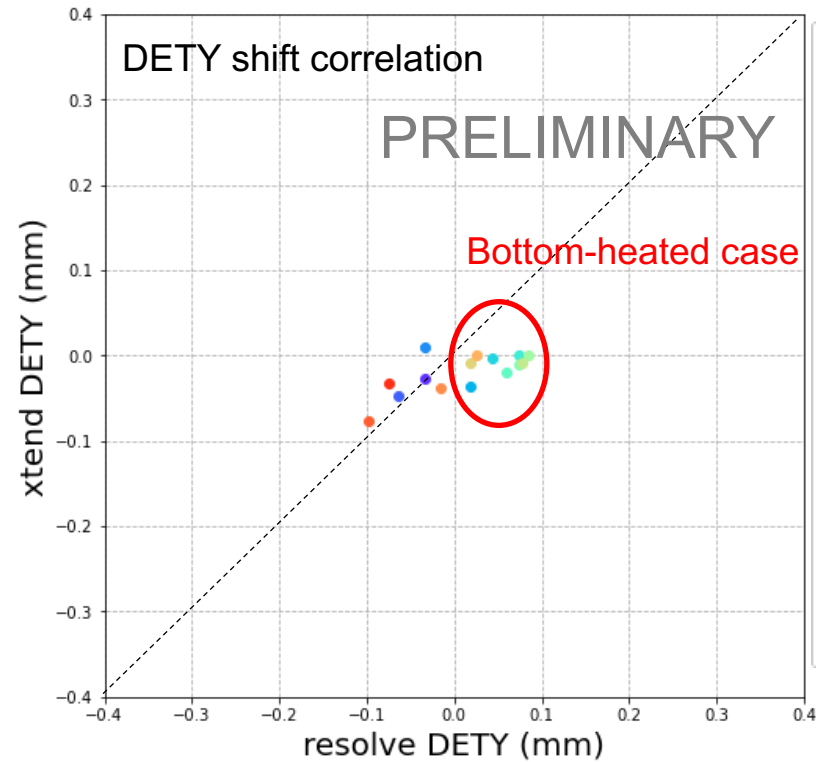
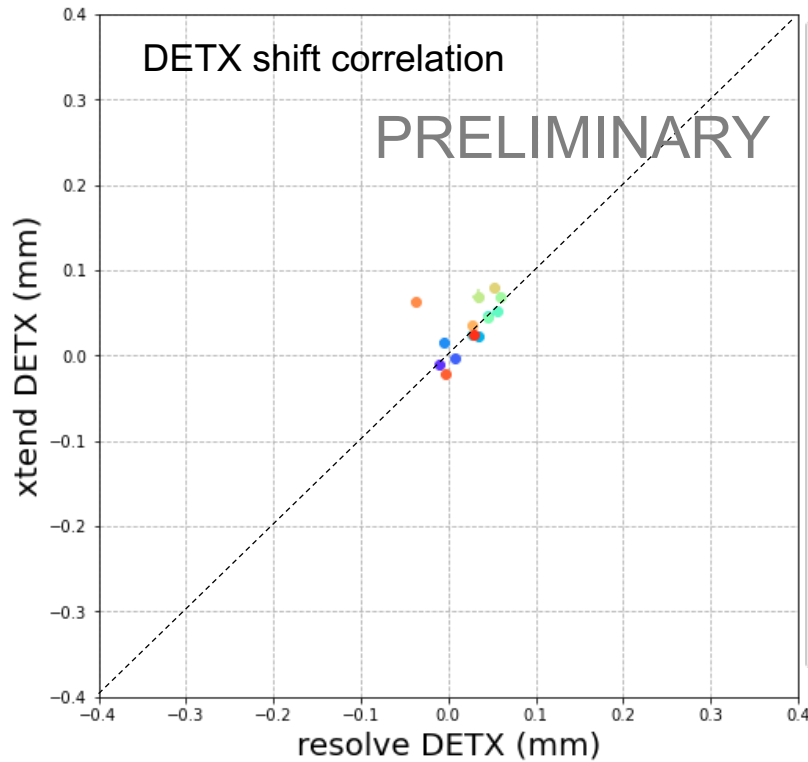
- Comparison of Resolve and Xtend
  - Dataset: observations after aimpoint search
  - Similar results to the aimpoint search observations.
  - Resolve's DETY shift remains in bottom-heated cases.





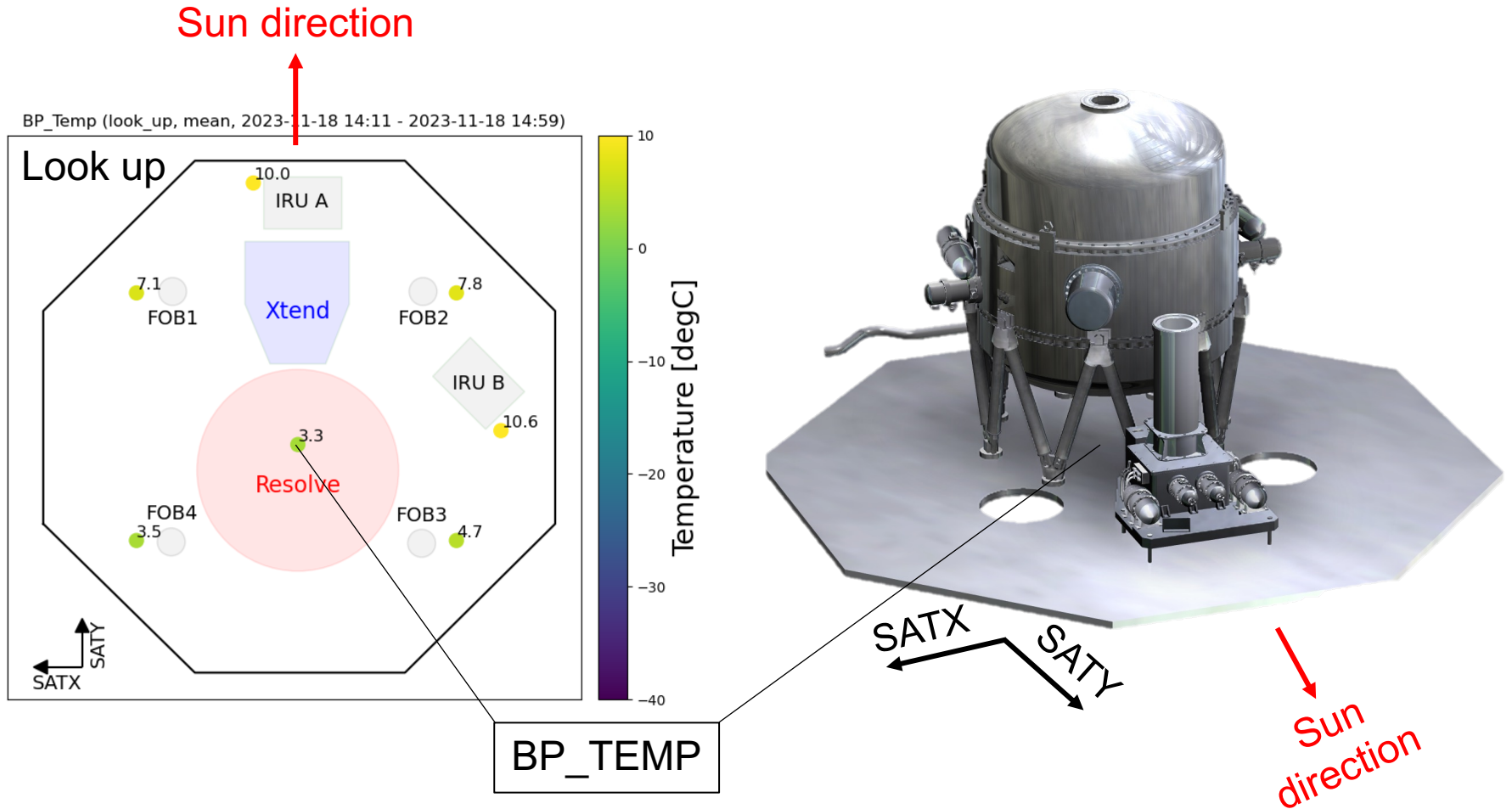
- Comparison of Resolve and Xtend
  - Dataset: observations after aimpoint search
  - Similar results to the aimpoint search observations.
  - **Resolve's DETY shift remains in bottom-heated cases.**

# Comparison of Resolve and Xtend



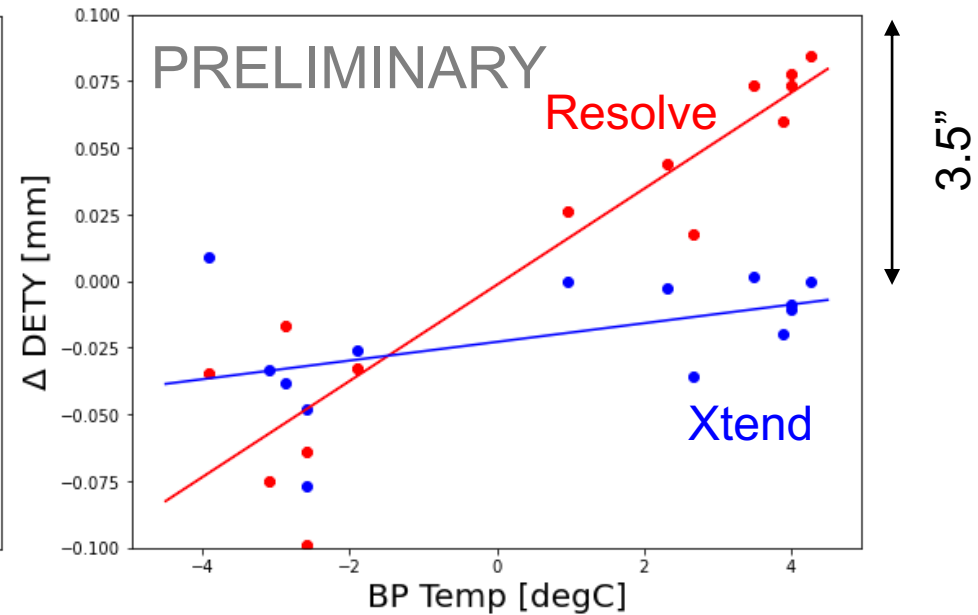
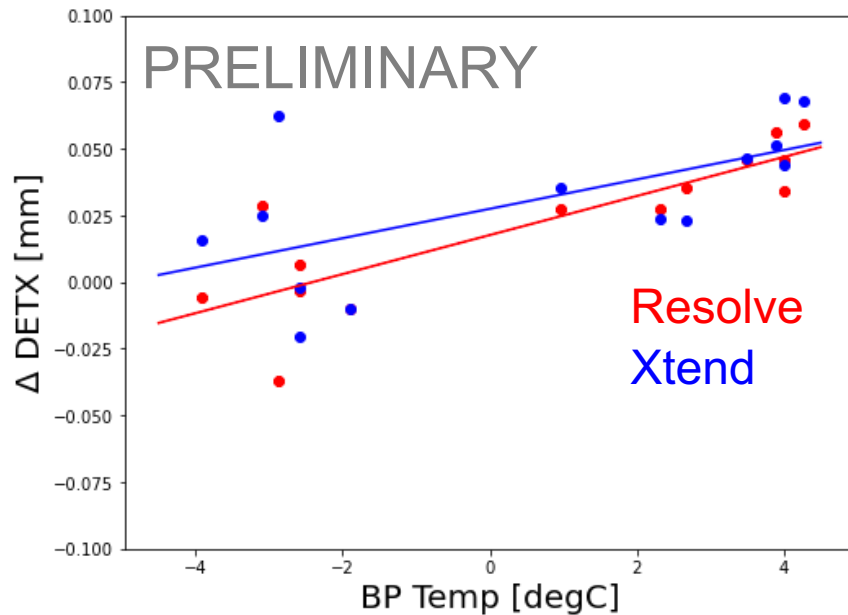
- Comparison of Resolve and Xtend
  - Dataset: observations after aimpoint search
  - DETX shifts of both detectors have a good correlation.
  - DETY shifts have different tendencies.

# BP temperature



- BP\_TEMP can increase up to 5 degrees Celsius in the bottom-heated case.

# Comparison of Resolve and Xtend



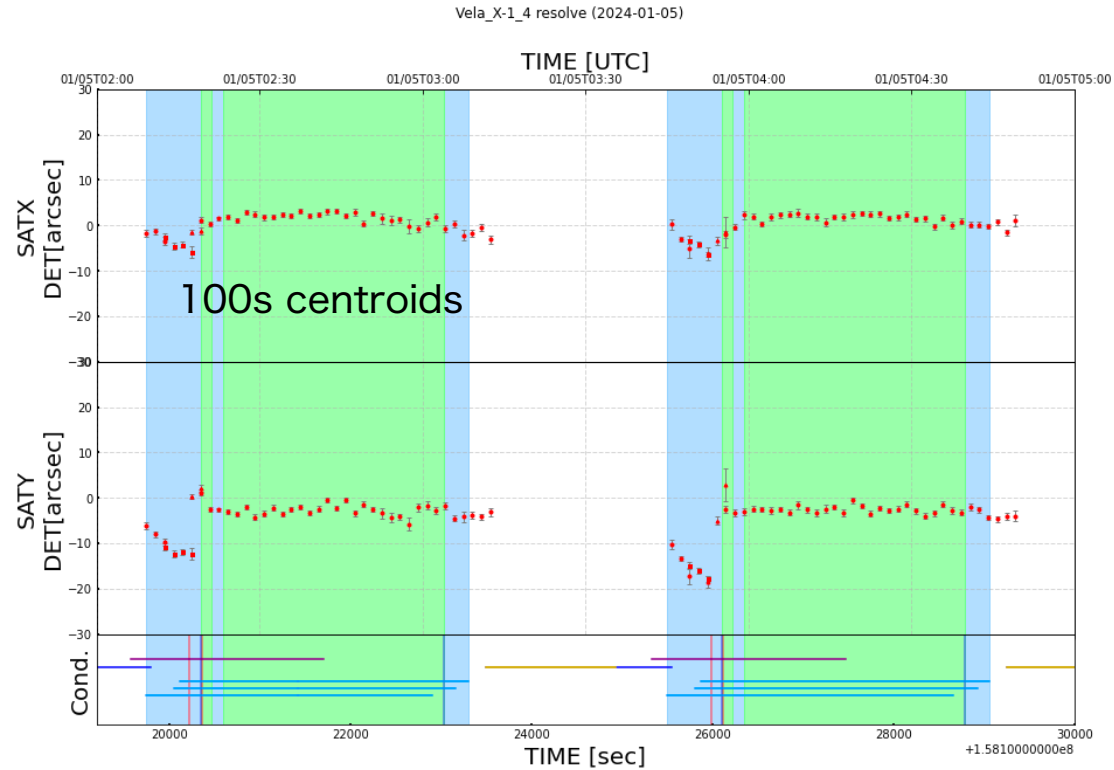
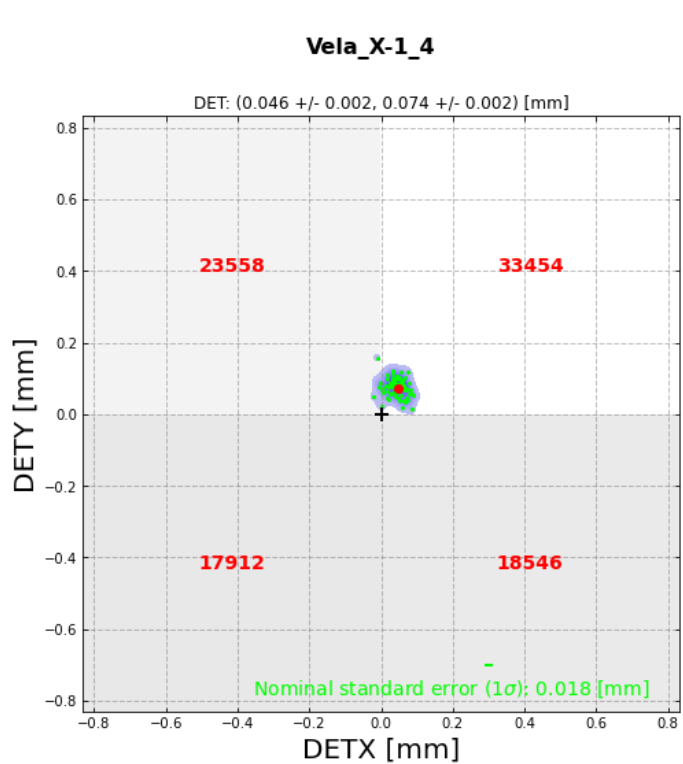
- BP\_TEMP can increase up to 5 degrees Celsius in the bottom-heated case.
- DETX shifts of both detectors have similar dependence.
- DETY shift of Resolve depends on BP temp due to the thermal strain.
- The shift amount is a few arcsec, though the shift is not corrected by attitude correction.



1. The shift amounts and directions of Resolve and Xtend are similar, except for the bottom-heated case.
2. DETX shifts of both detectors have a good correlation.
3. DETY shift of Resolve is likely to depend on BP temperature. The typical amount is a few arcsecs in the bottom-heated case.

# **Control and Determination accuracy**

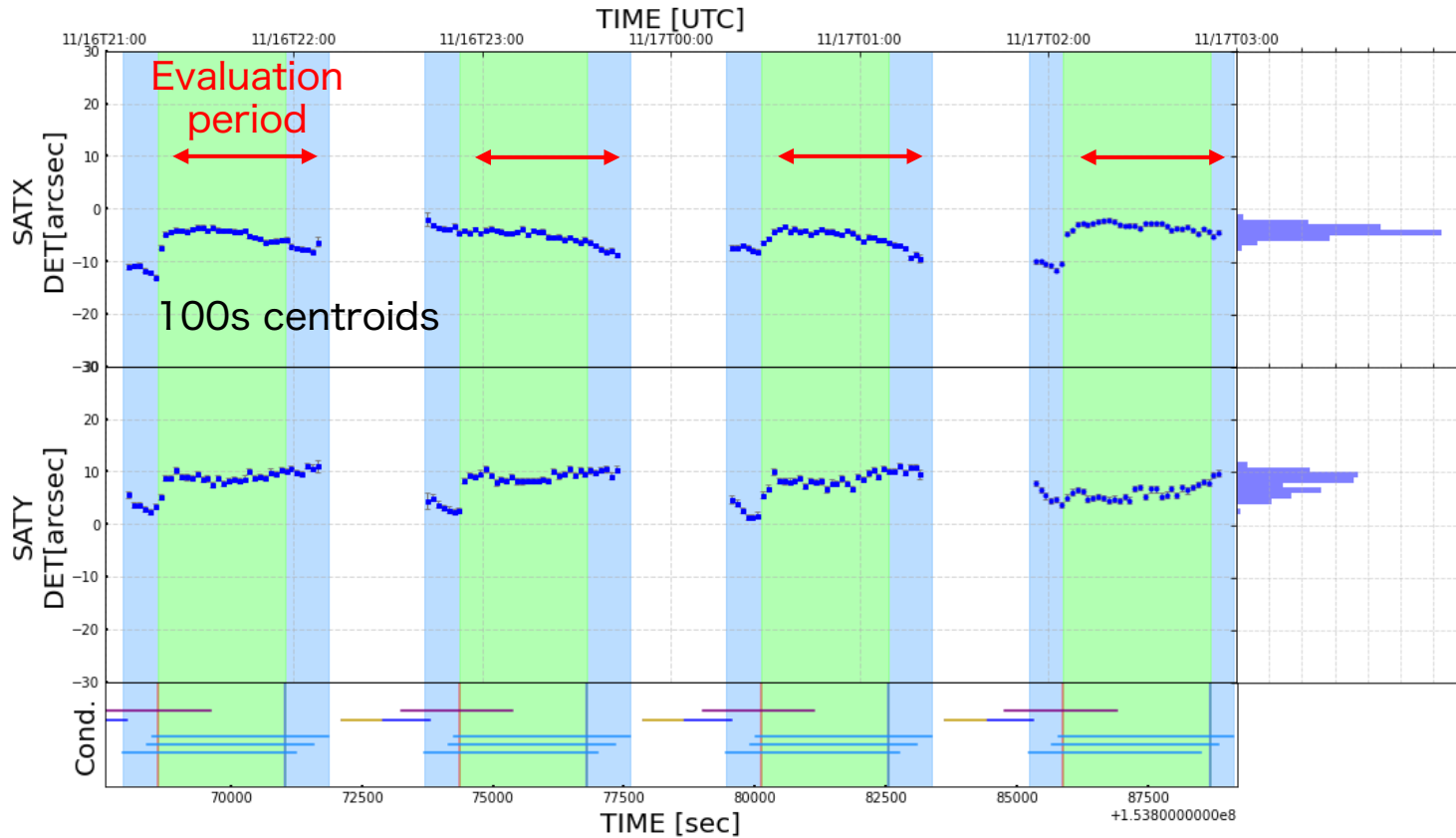




- Control and determination accuracies are analyzed by the trend of 100-sec centroids from Resolve and Xtend data.
  - Control accuracy: AOCs control
  - Determination accuracy: Attitude offline processing

# Attitude Control accuracy

LMC\_X-3\_Case5\_xtend (2023-11-16)



- Control accuracy was evaluated by the X-ray photon centroids in DET coordinates after the convergence of the Kalman filter.

	Measurement ( $3\sigma$ )	Requirement ( $3\sigma$ )
<b>Resolve</b>	$15.0 \pm 1.2''$	55''
<b>Xtend</b>	$52.3 \pm 0.5''$ (*)	184''

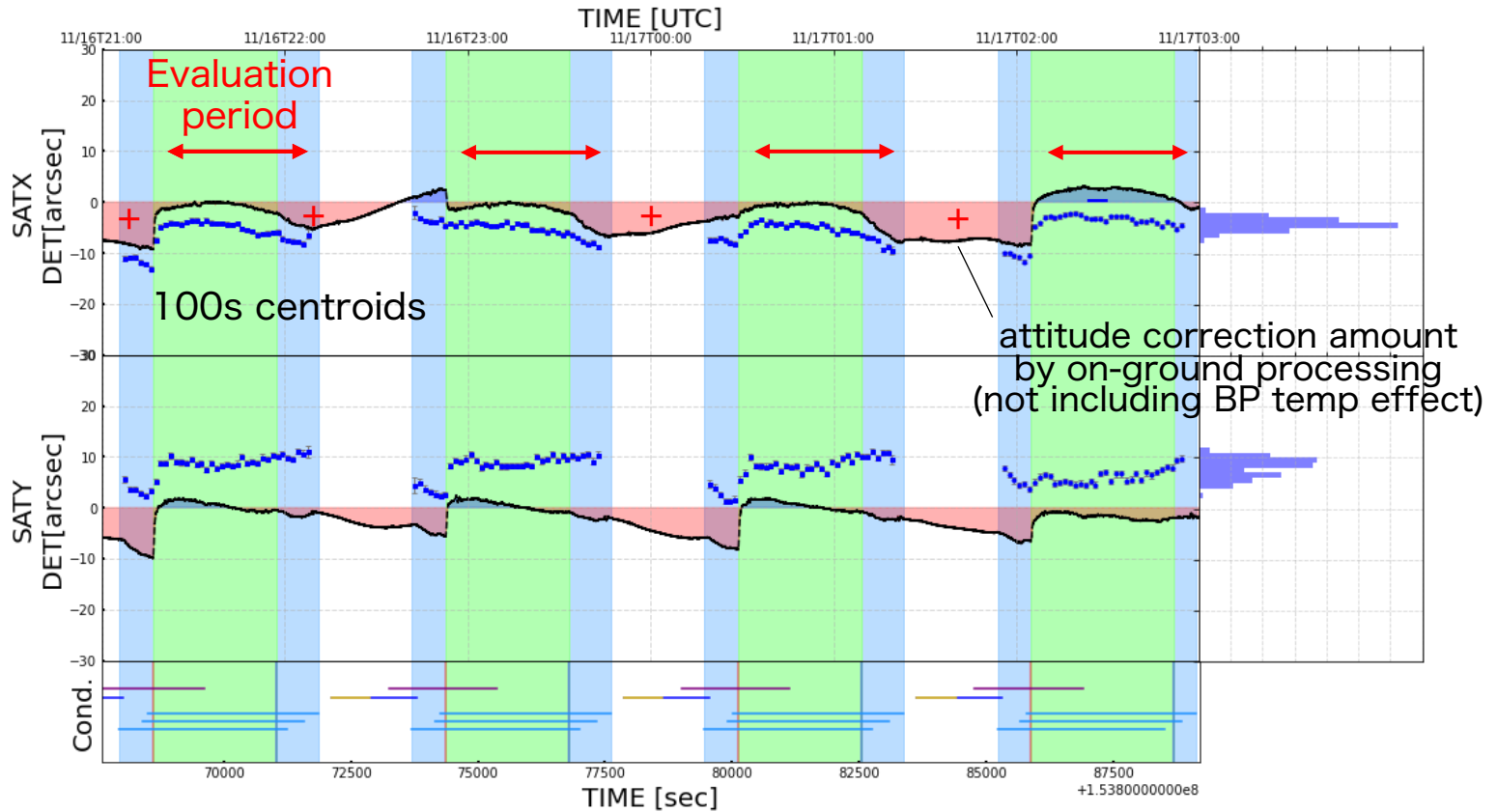
Requirements are Satisfied.

- Including aimpoint shift and orbital variation.

- (\*) Xtend result includes a deviation of 38.2'' from the ground measurement.

# Attitude Control accuracy

LMC\_X-3\_Case5\_xtend (2023-11-16)



- Control accuracy was evaluated by the X-ray photon centroids in DET coordinates after the convergence of the Kalman filter.

	Measurement (3 $\sigma$ )	Requirement (3 $\sigma$ )
<b>Resolve</b>	15.0 $\pm$ 1.2''	55''
<b>Xtend</b>	52.3 $\pm$ 0.5'' (*)	184''

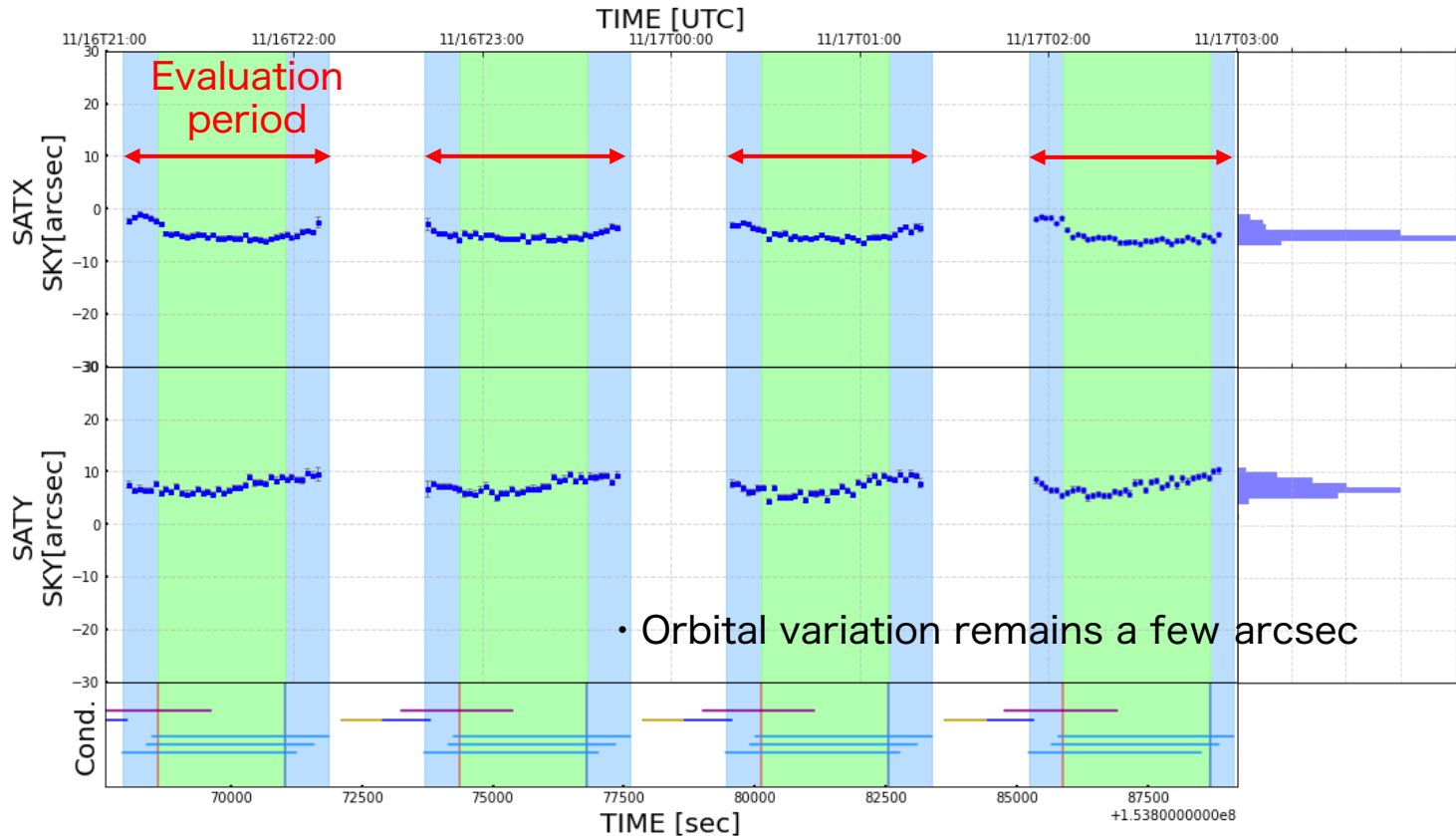
**Requirements are Satisfied.**

- Including aimpoint shift and orbital variation.

- (\*) Xtend result includes a deviation of 38.2'' from the ground measurement.

# Determination accuracy

LMC\_X-3\_Case5 xtend (2023-11-16)



- Determination accuracy was evaluated by the X-ray photon centroids in SKY coordinates during the time at least one STT is activated.

	Measurement (3 $\sigma$ )	Requirement (3 $\sigma$ )
<b>Resolve</b>	17.4 $\pm$ 1.5''	20''
<b>Xtend</b>	17.0 $\pm$ 1.0''	20''

**Requirements are Satisfied.**

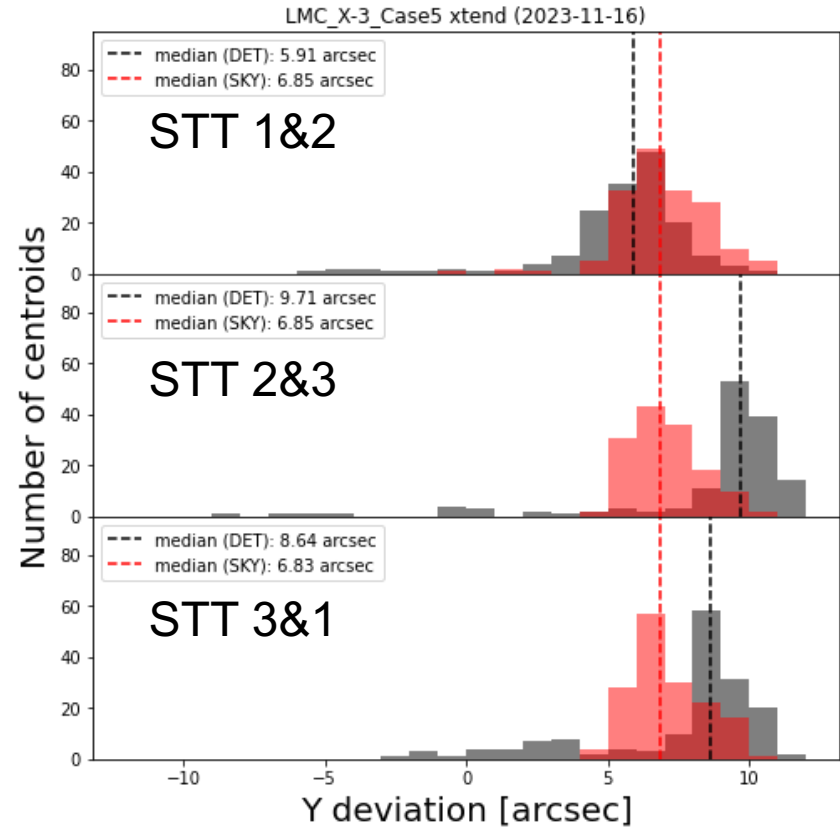
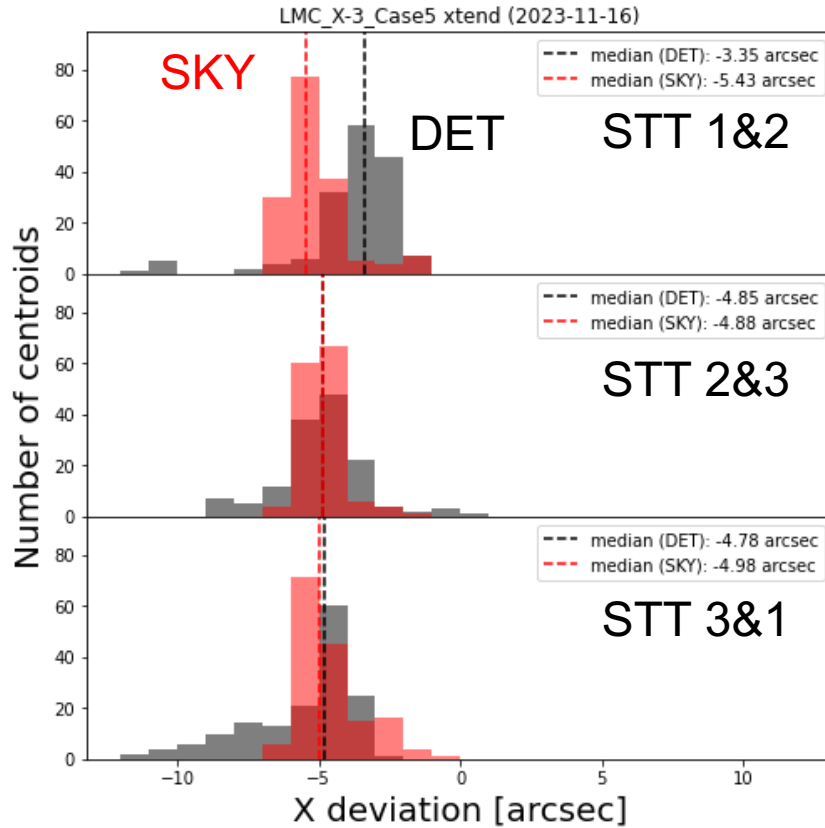
- Including aimpoint shift and orbital variation.

- Attitude correction methods are almost complete in the commissioning phase, though we are considering the need for a minor update.

1. On-axis determination accuracy is generally less than 20" @  $3\sigma$ .
2. X-ray photon centroid trends of Resolve and Xtend are very similar including bottom-heated case. The aimpoint shift can be treated as a fixed bias.
3. A few arcsec orbital variation still exists in some observations after the update. We are still investigating the cause.
4. The commissioning result doesn't include the annual variation. Pointing accuracy analysis is still ongoing.

# Backup

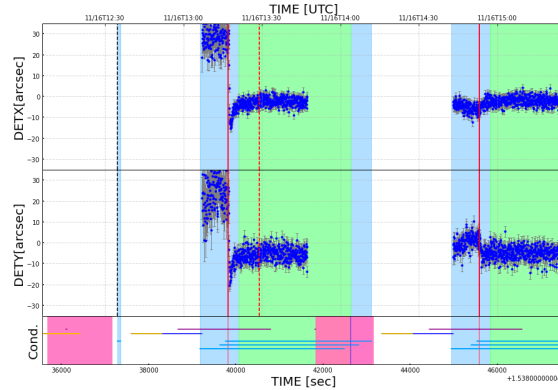
# STT bias correction





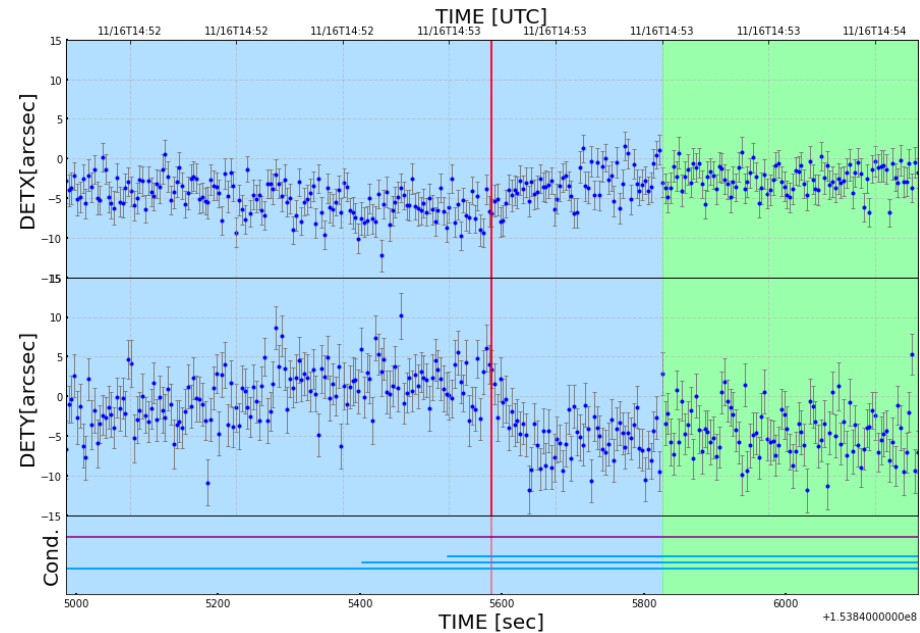
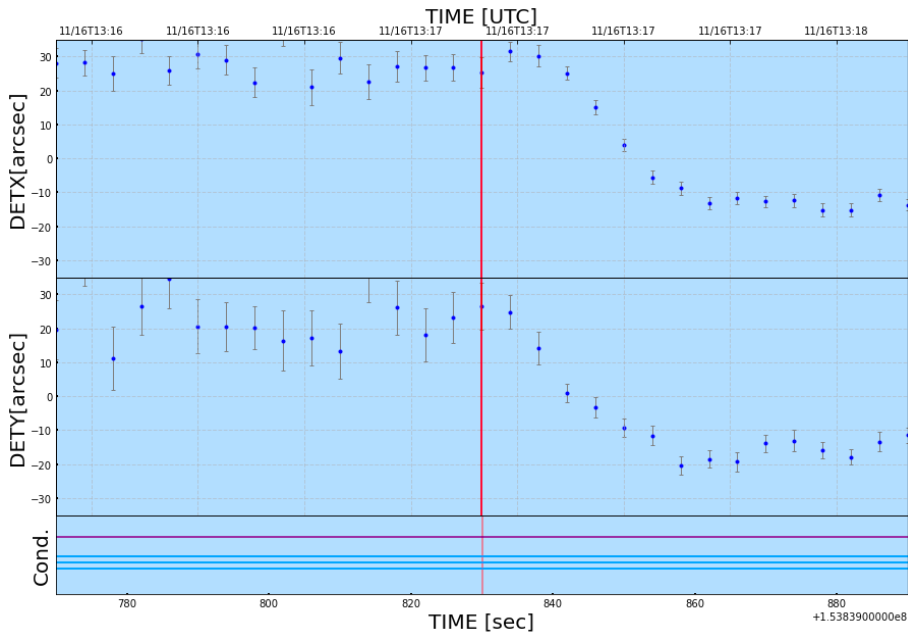
# 4-sec centroids for 1<sup>st</sup> & 2<sup>nd</sup> Revolutions

1<sup>st</sup> Rev.      2<sup>nd</sup> Rev.

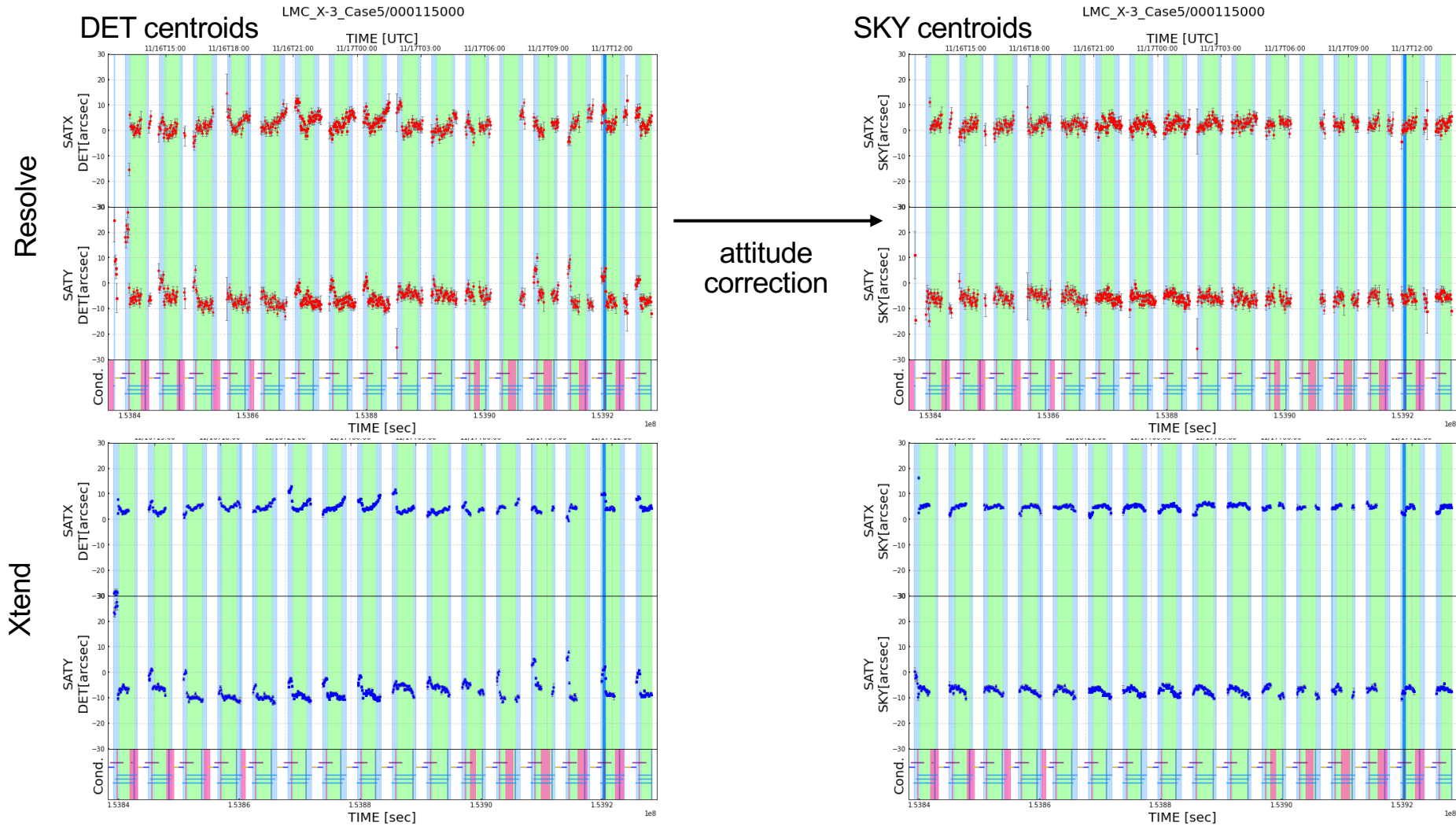


The speed after MNV is a few arcsec/sec.

The attitude converged within 240 seconds



# Attitude determination accuracy



- The trends of Resolve and Xtend in DET and SKY coordinates are similar.
- **Attitude correction reduces the deviations  $< \sim 10''$**  by offline processing in PPL.
- A few arcsec orbital variation still exists in some observations after updating PPL.